

Trainingsroboter

Mechanischer Aufbau

Entwicklung und Herstellung:

fischerwerke

Artur Fischer GmbH & Co. KG

Weinhalde 14 - 18

72178 Waldachtal

Deutschland

Scan:

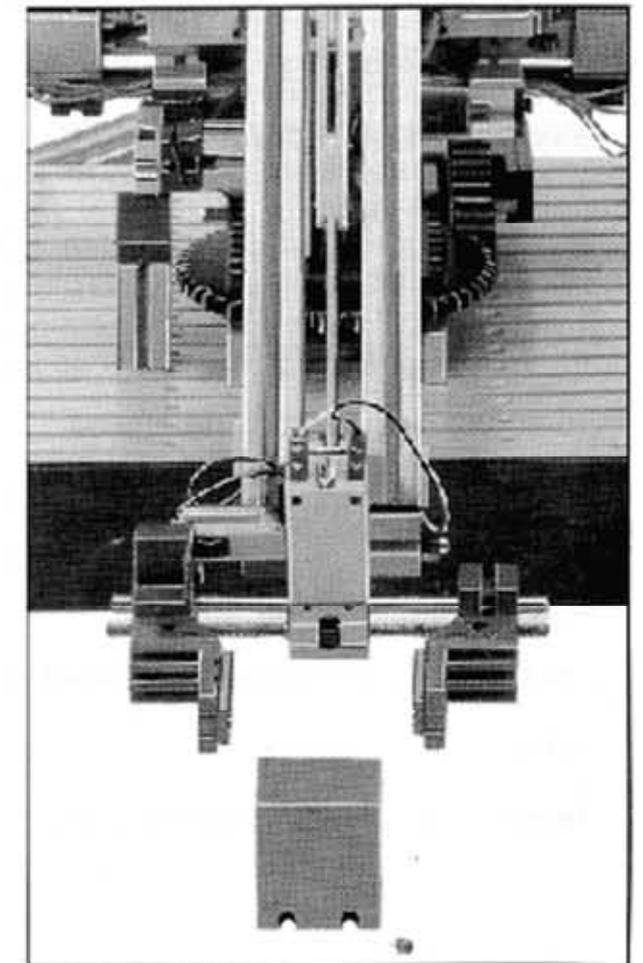
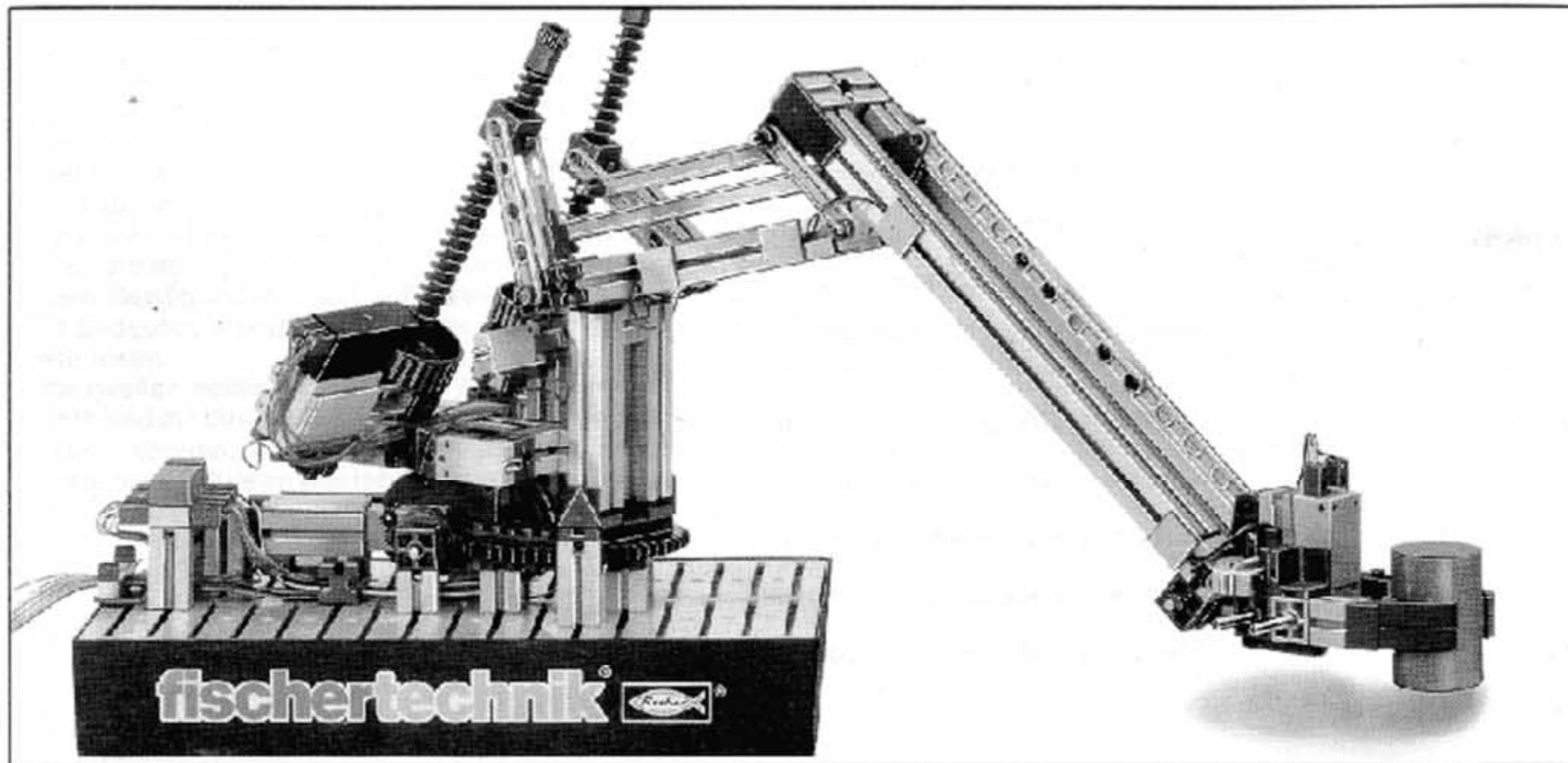
Andreas Stabinger, Heßstraße 48, 80798 München

Bitte beachten:

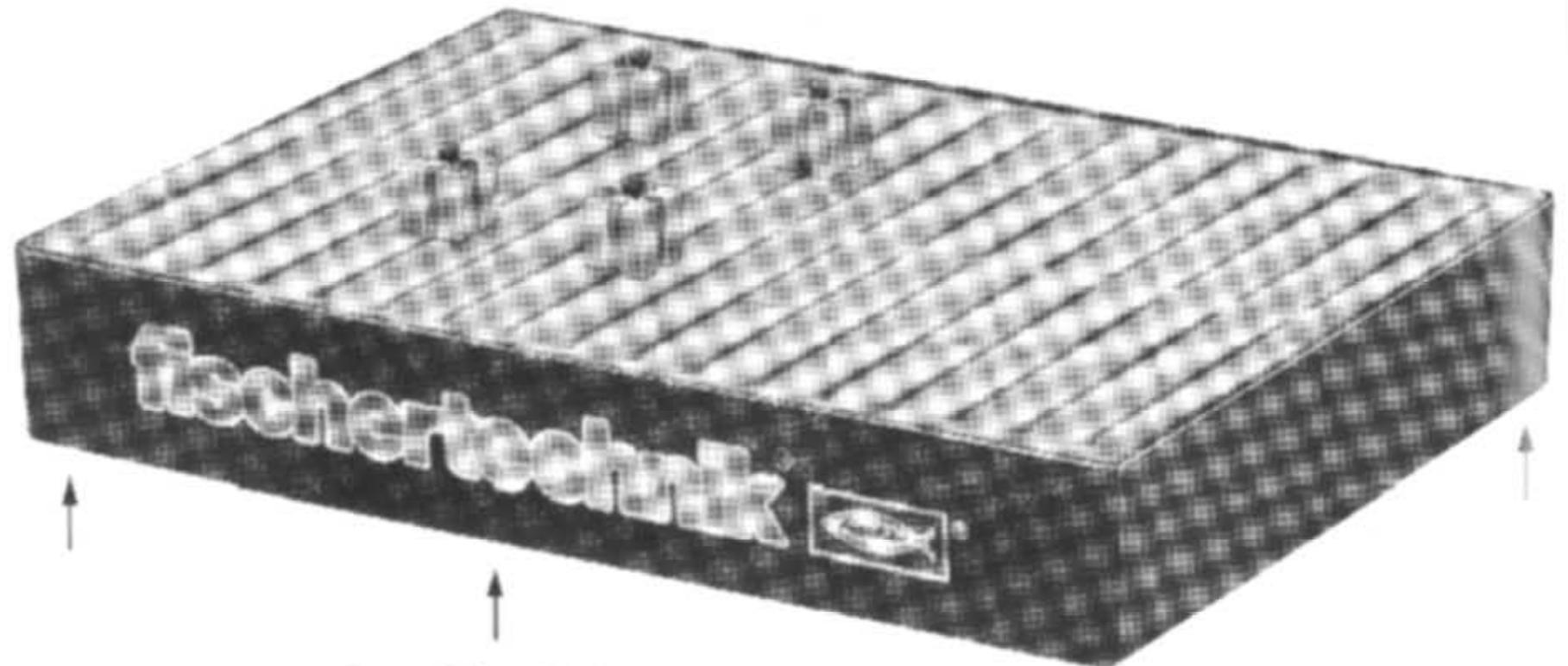
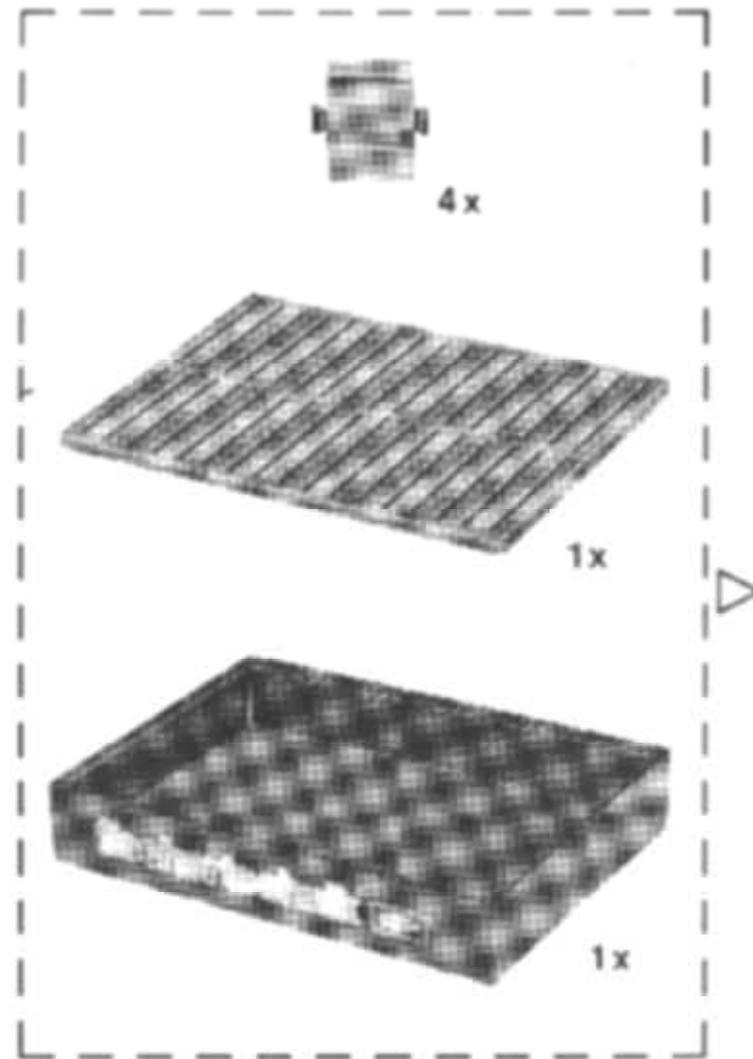
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fischertechnik® COMPUTING

Bauanleitung Trainingsroboter · Instructions Training Robot · Mode d'emploi du robot d'entraînement

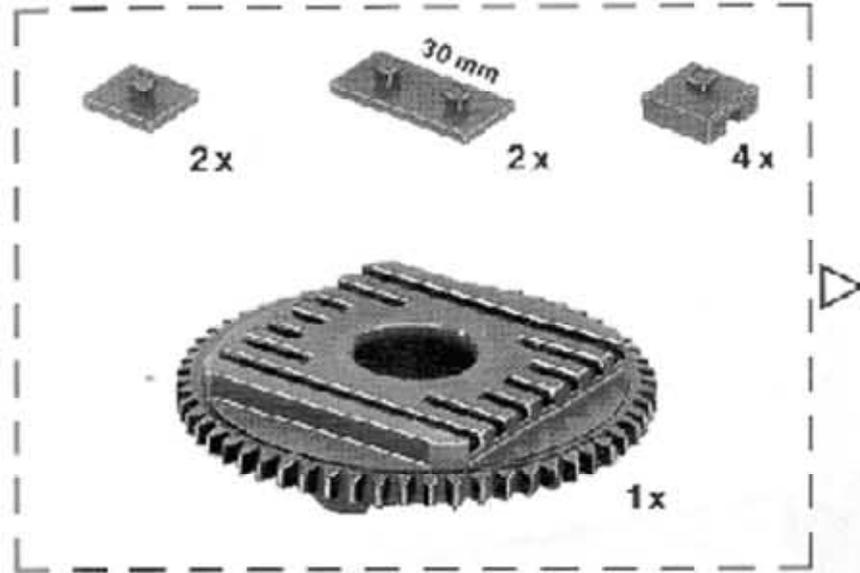


1

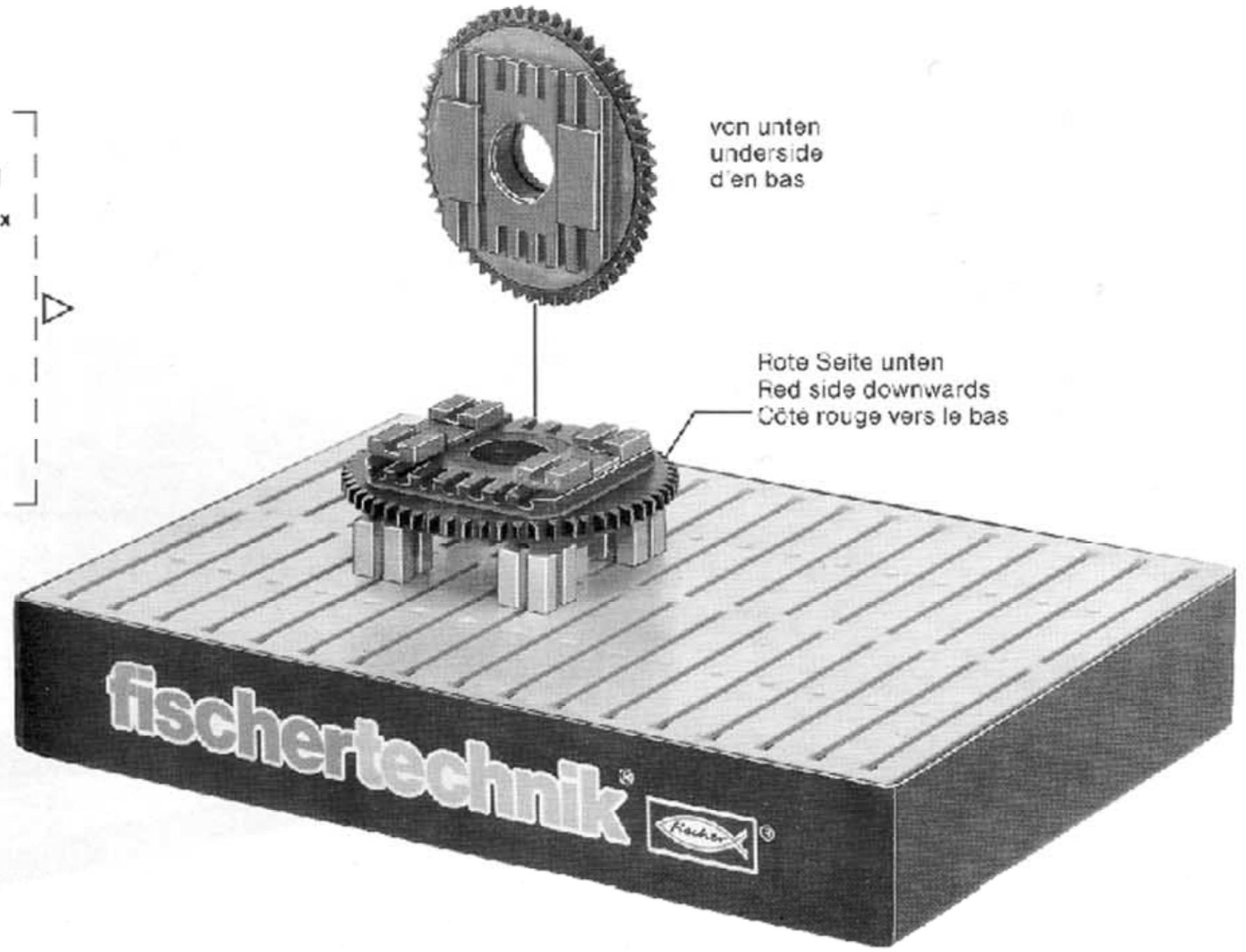


GummifüÙe aufkleben
Place selfadhesive pads
Coller les pieds en caoutchouc

2



0 30 mm

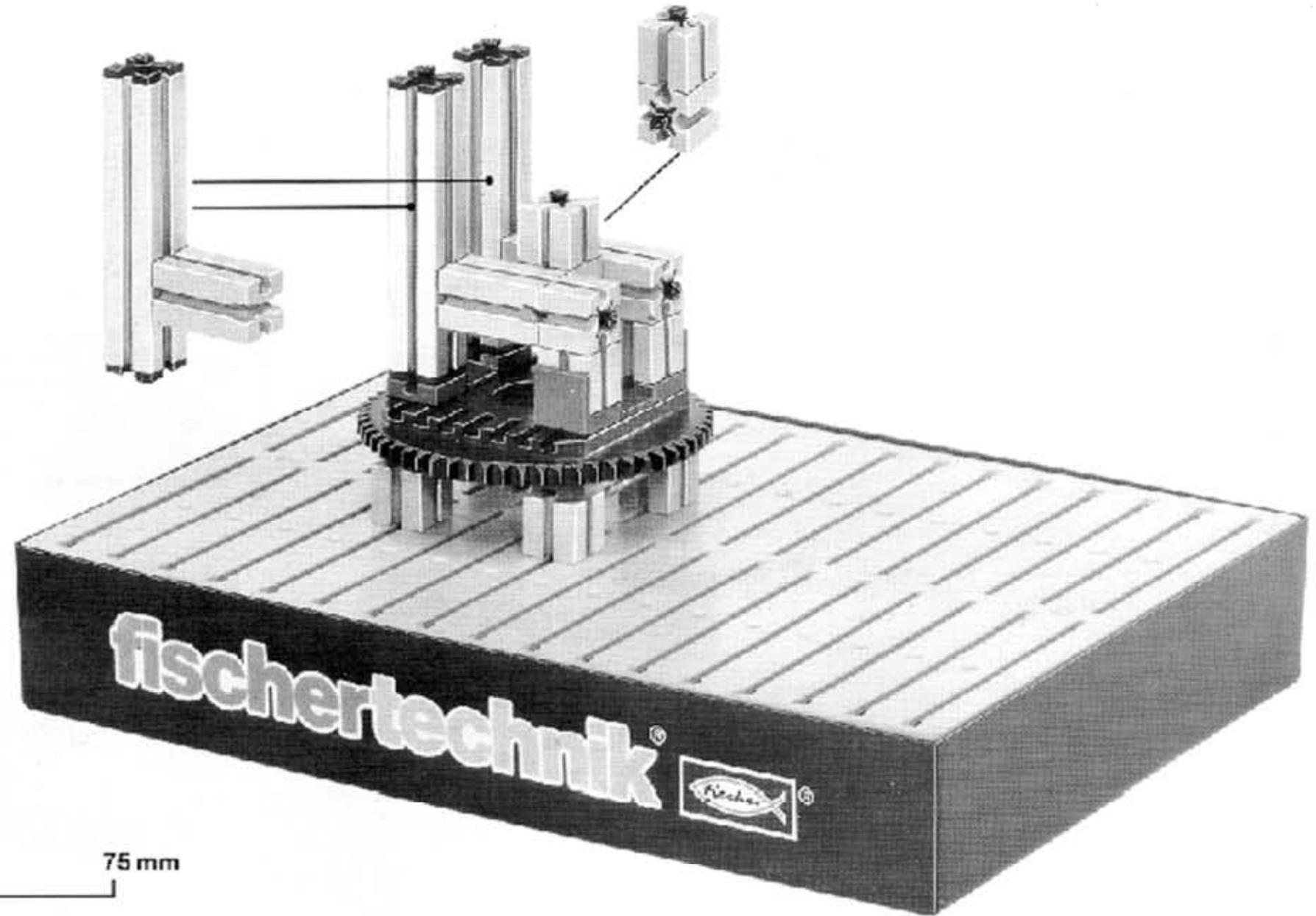
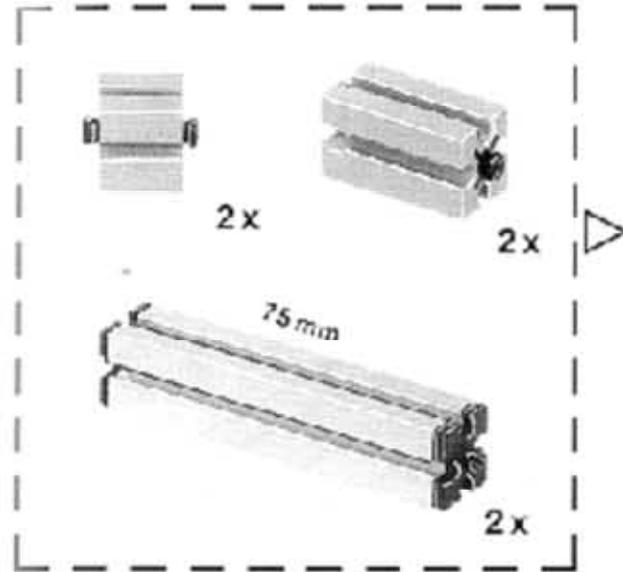


4

Aus technischen Gründen sind die Scherkräfte der Metalbaustäbe teilweise sehr hoch.

For technical reasons, the shearing forces of the structural metal rods are partially very high.

Pour des raisons techniques les forces transversales des barres métalliques de construction sont parfois très importantes.

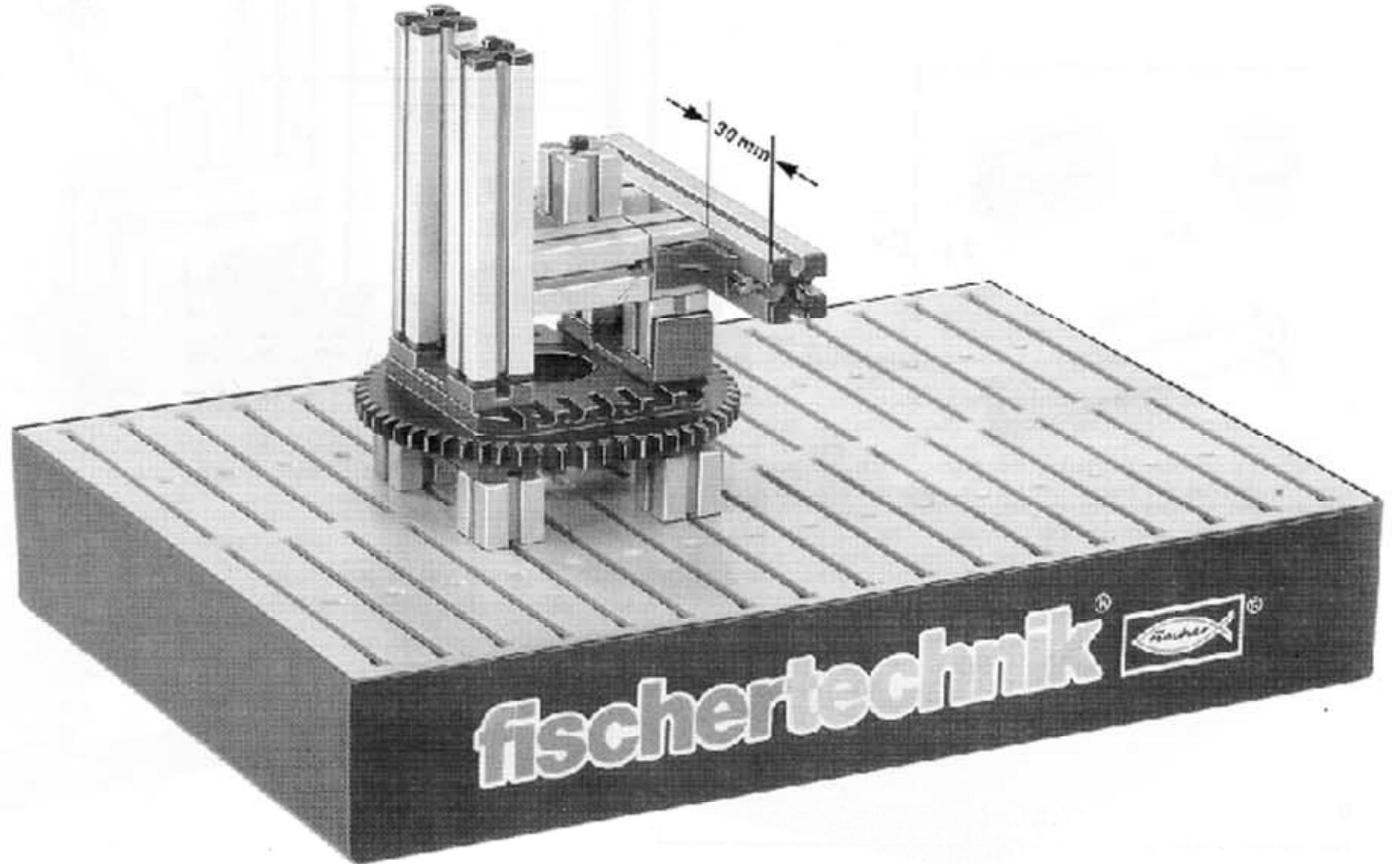
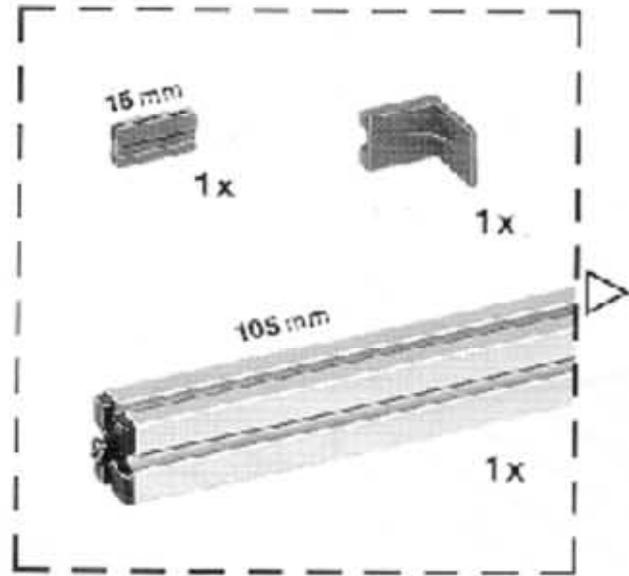


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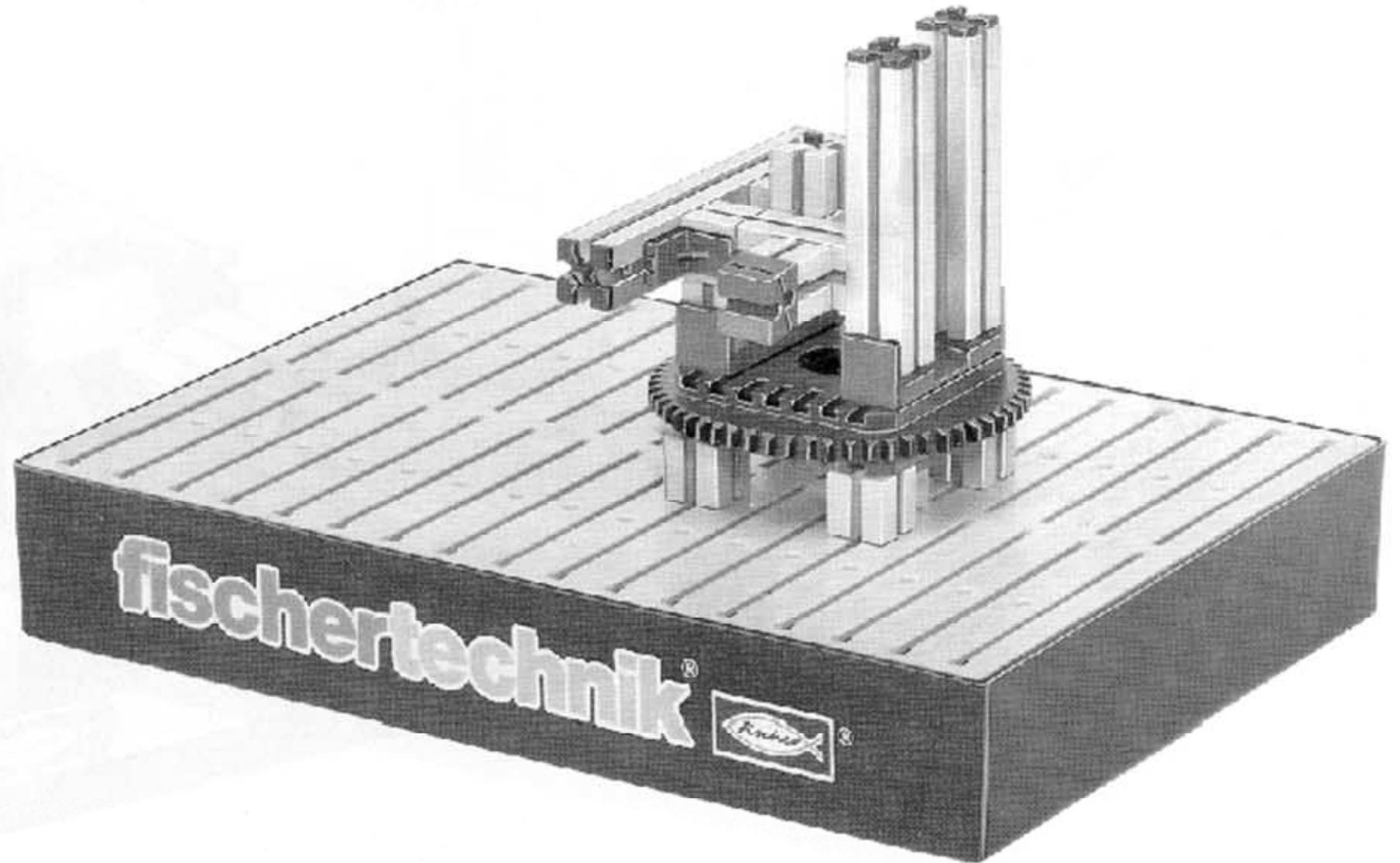
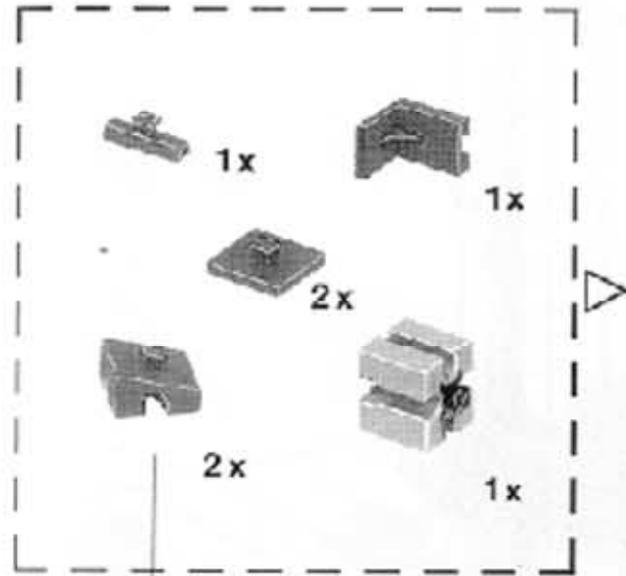
For technical reasons the shearing force of the structural metal rods is cavity very high.

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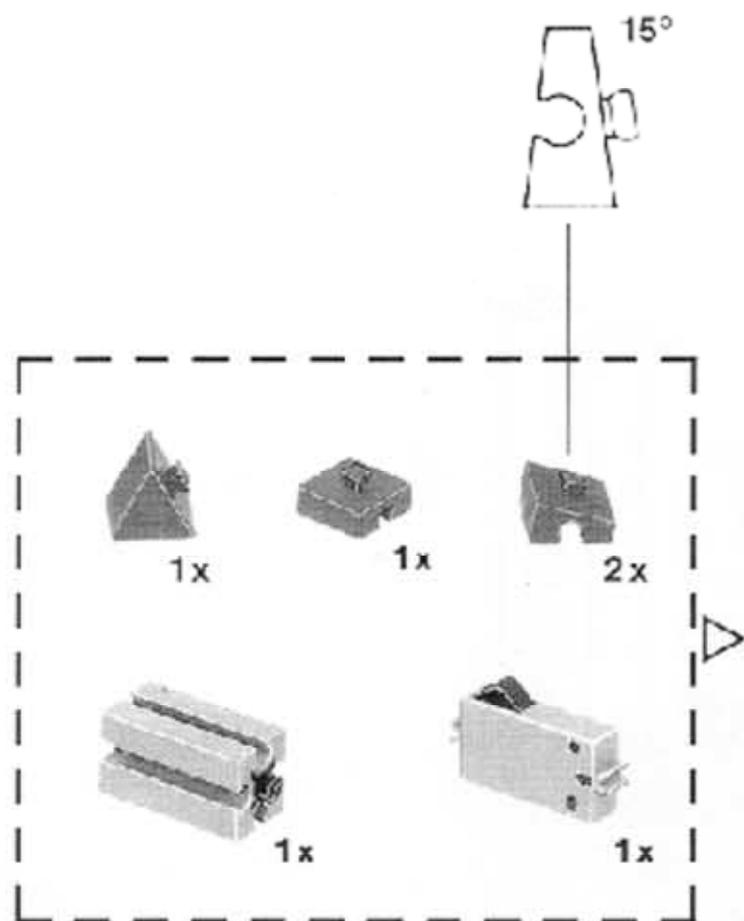
For technical reasons the shearing force of the structural metal rods is cavity very high.

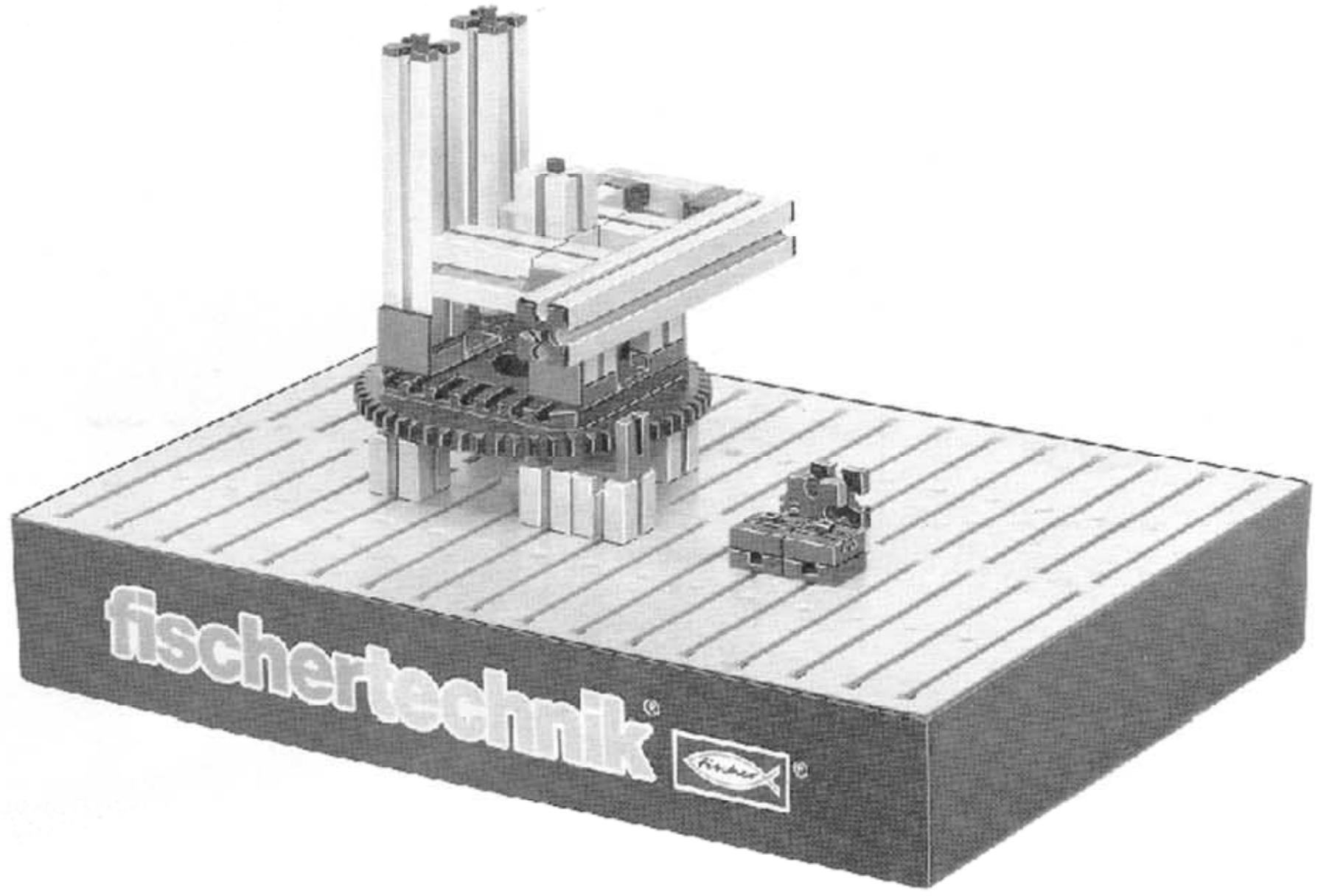
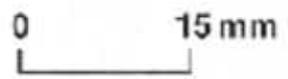
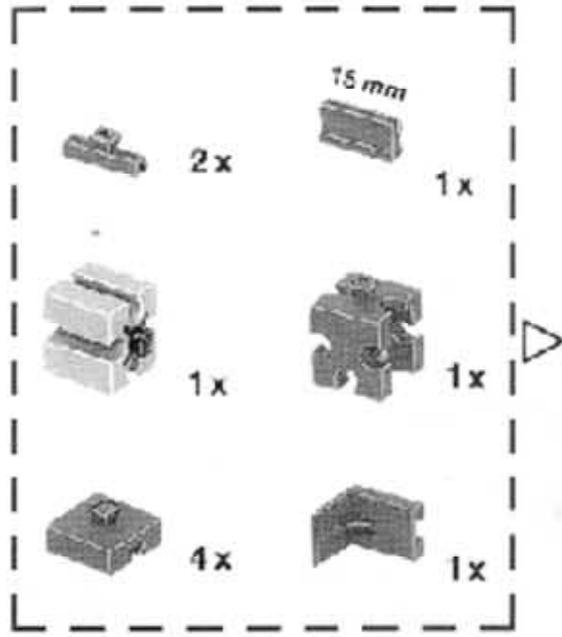


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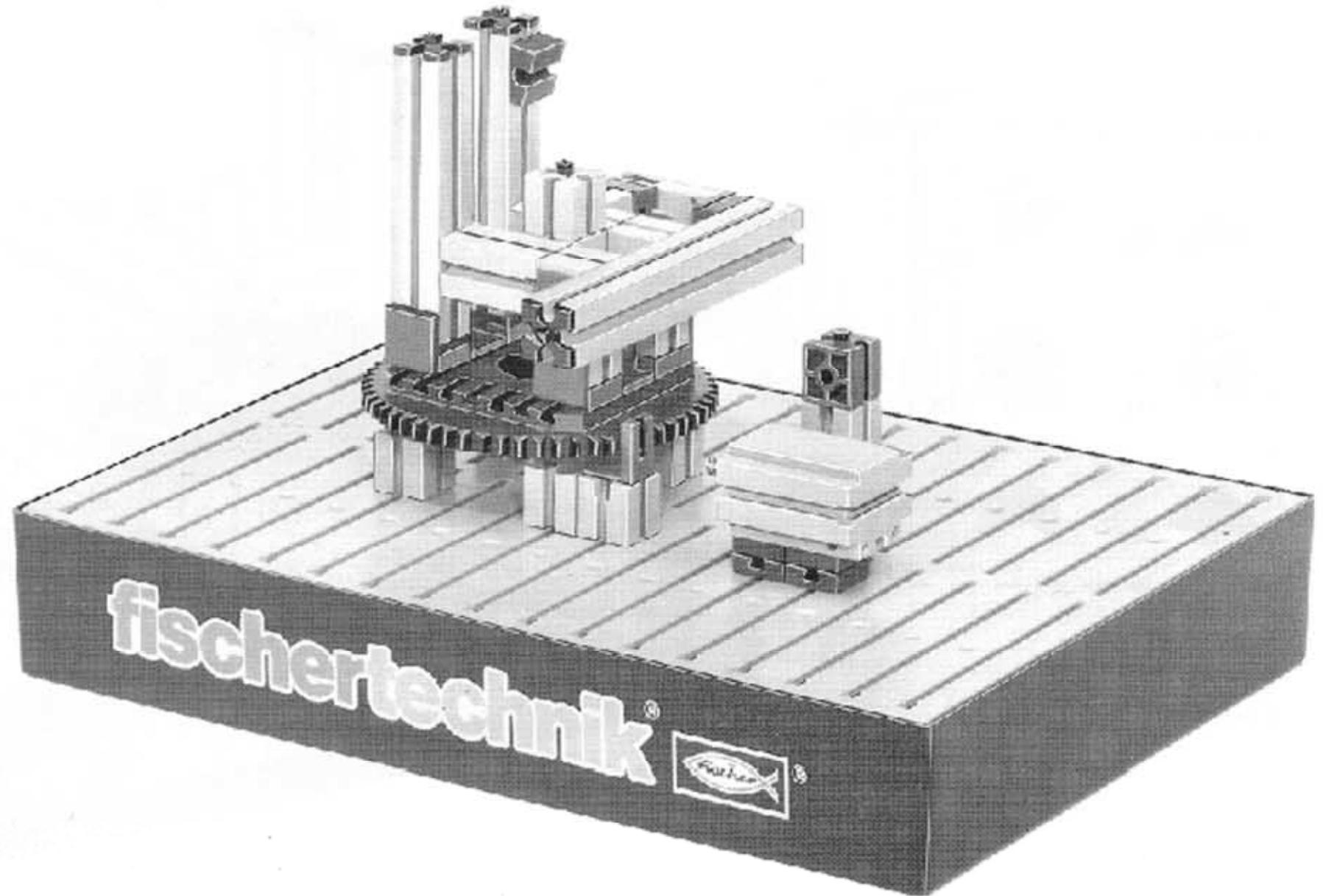
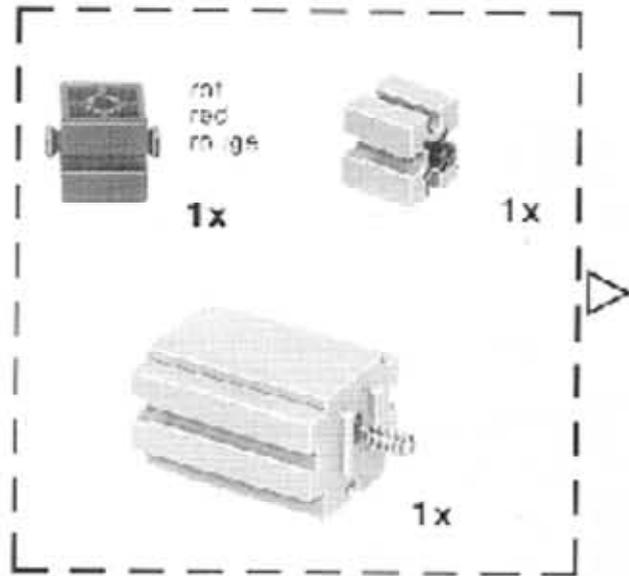
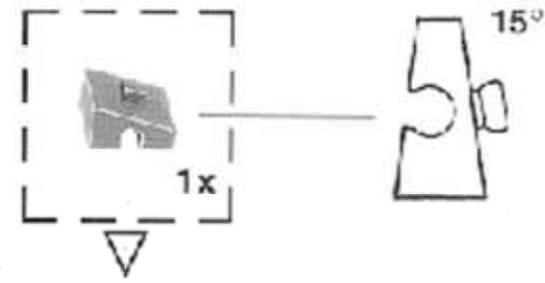


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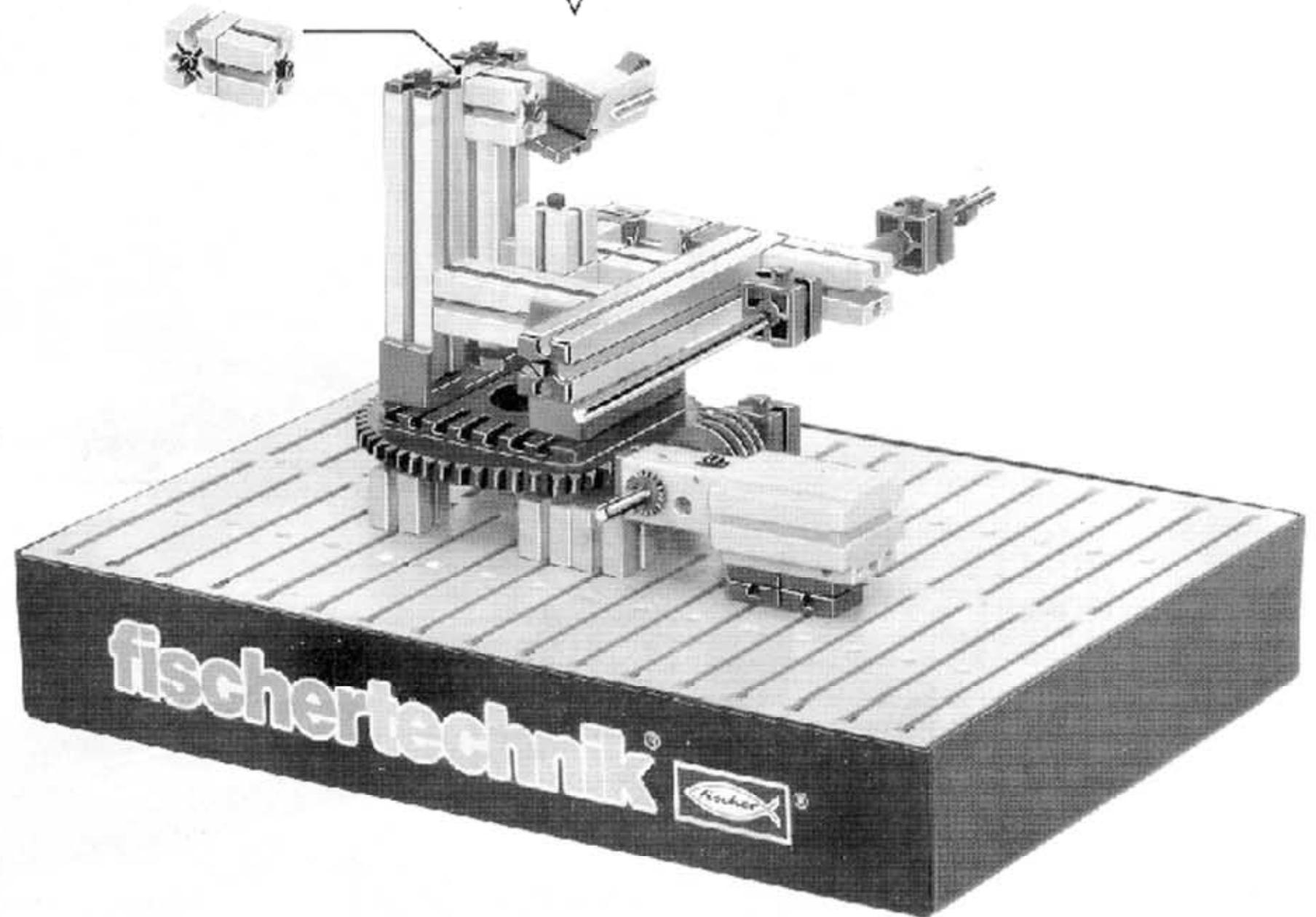
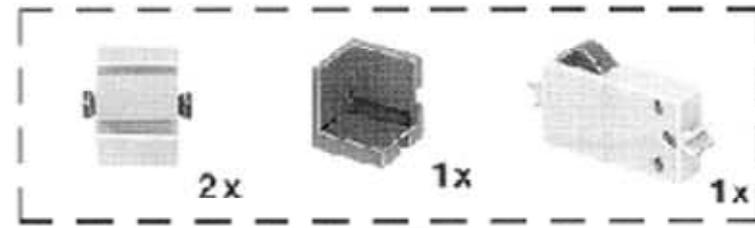
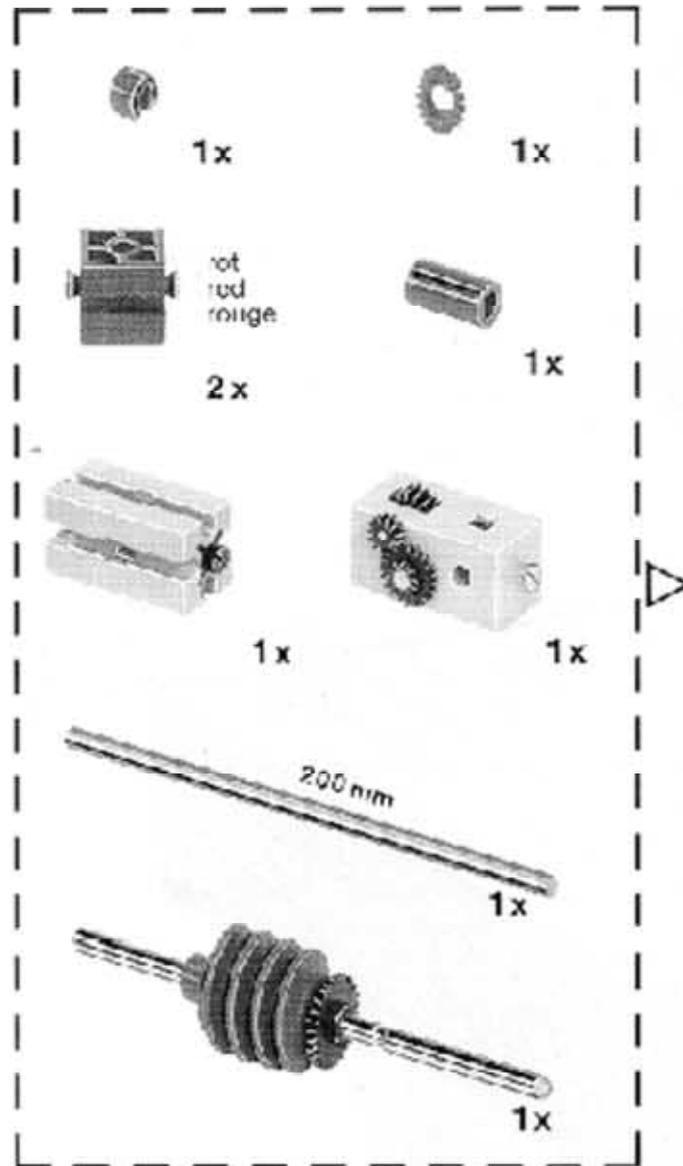




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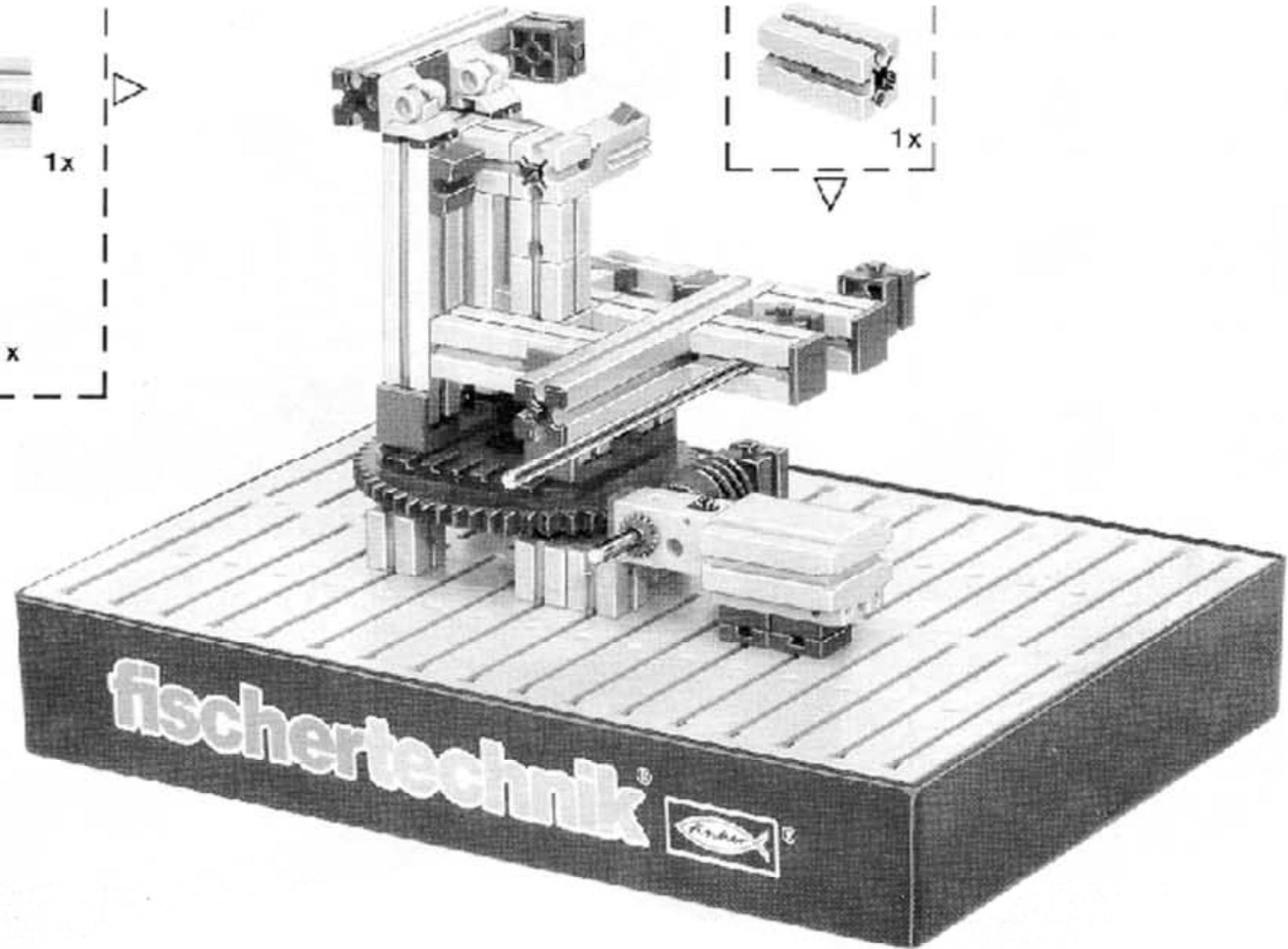
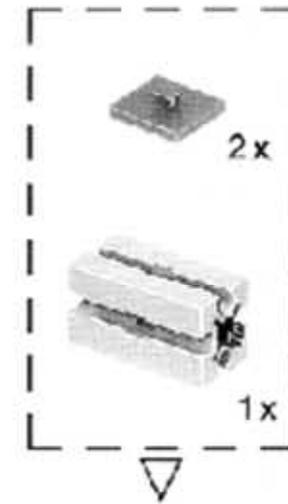
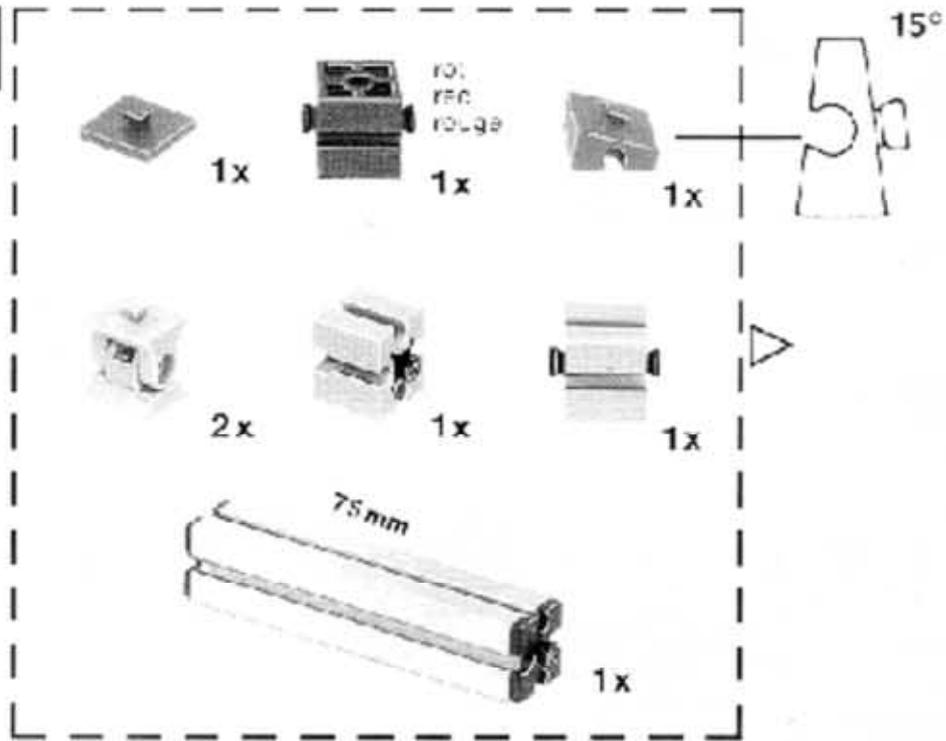
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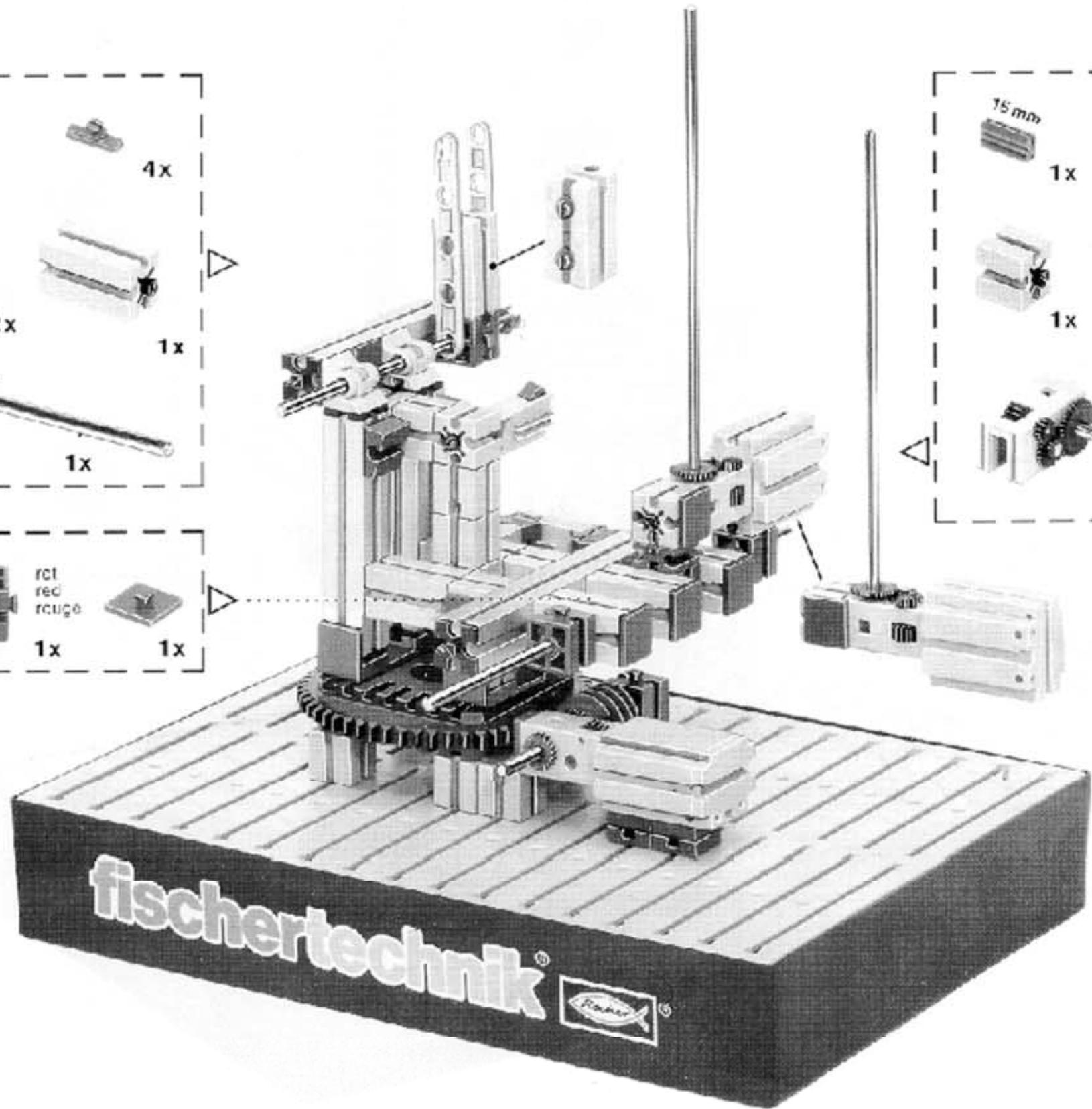
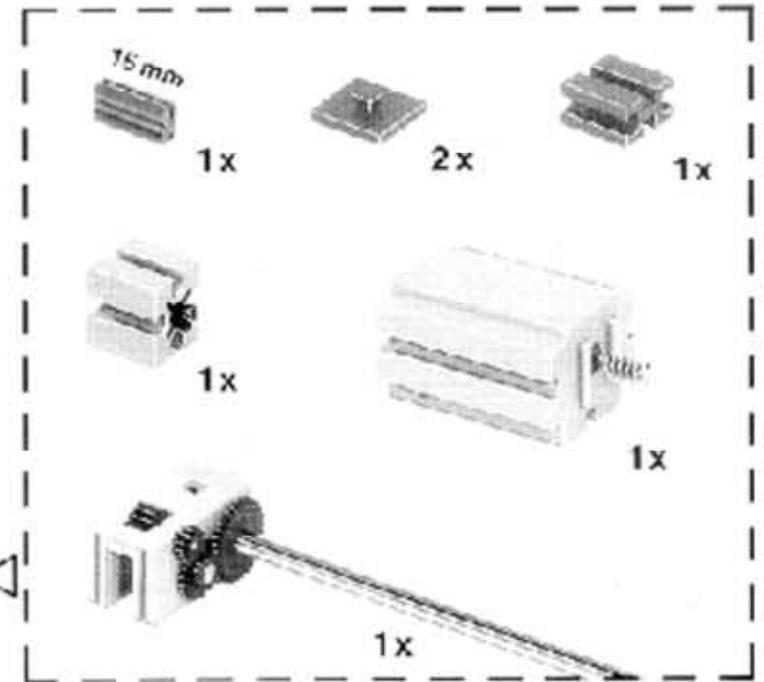
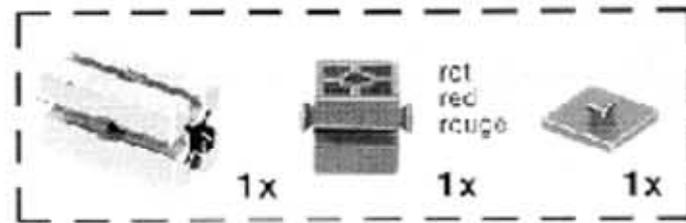
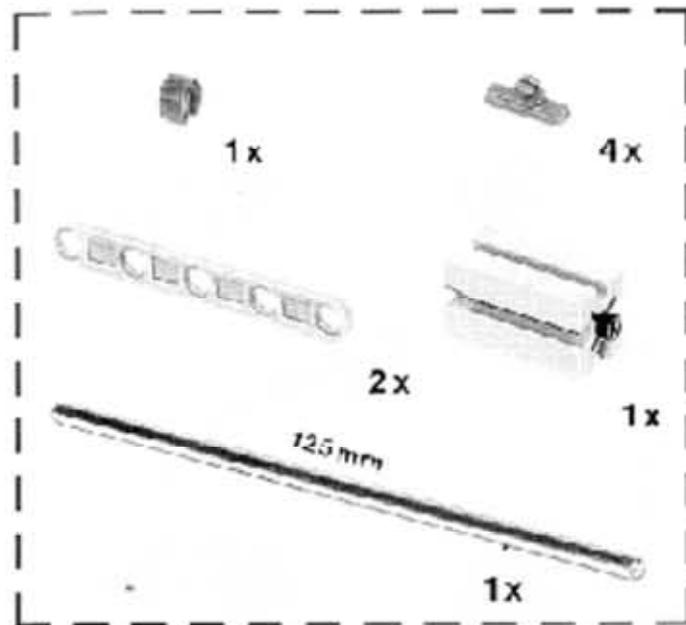
0

200 mm

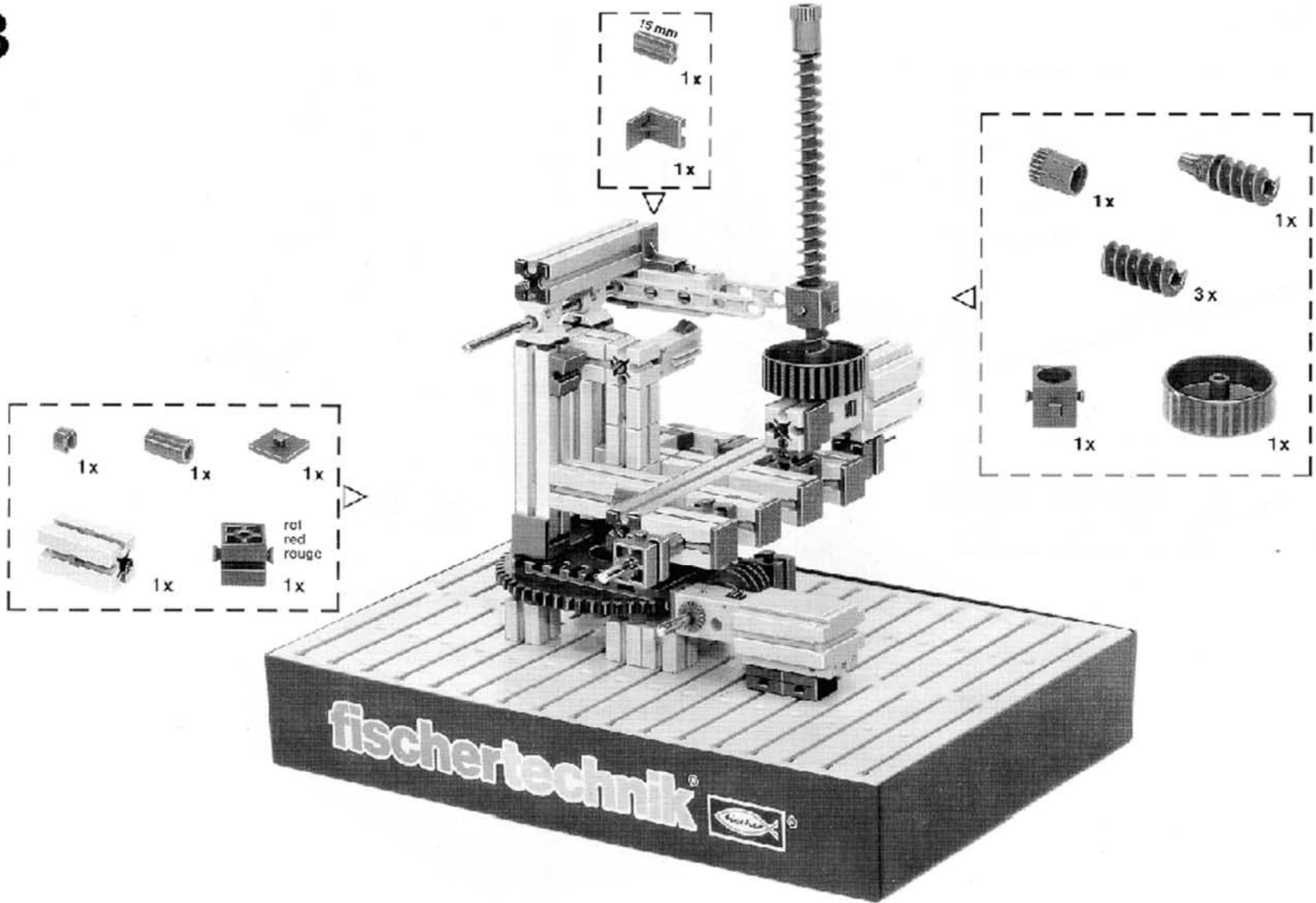
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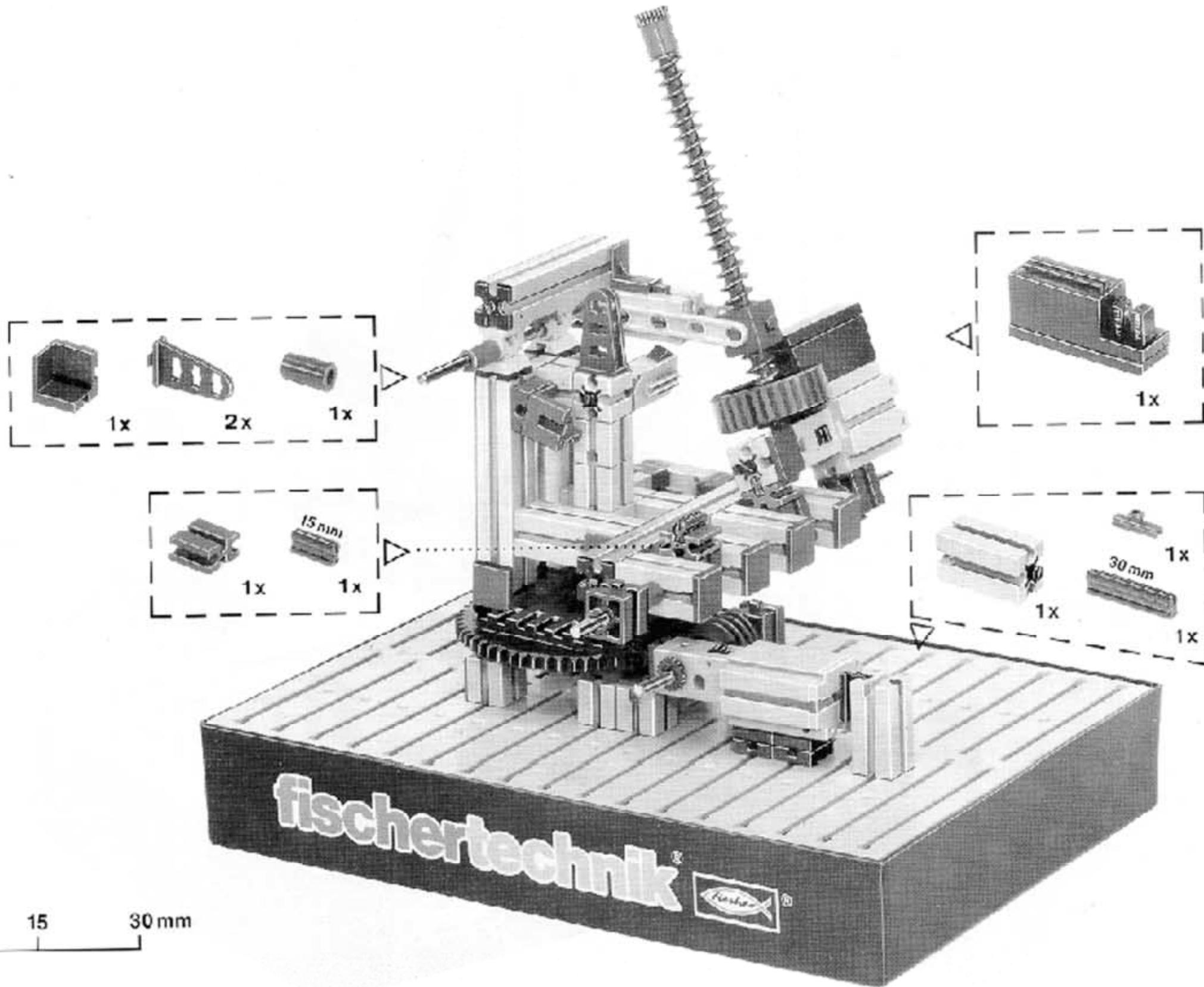


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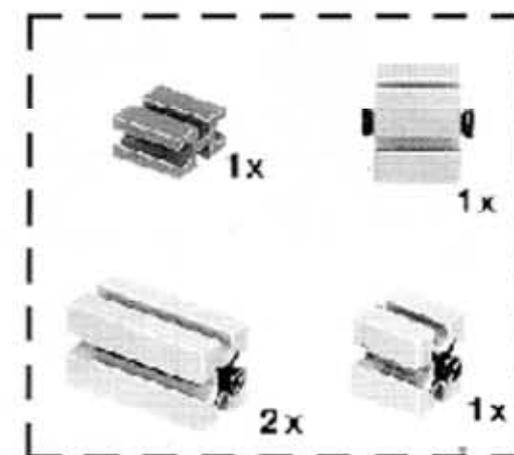
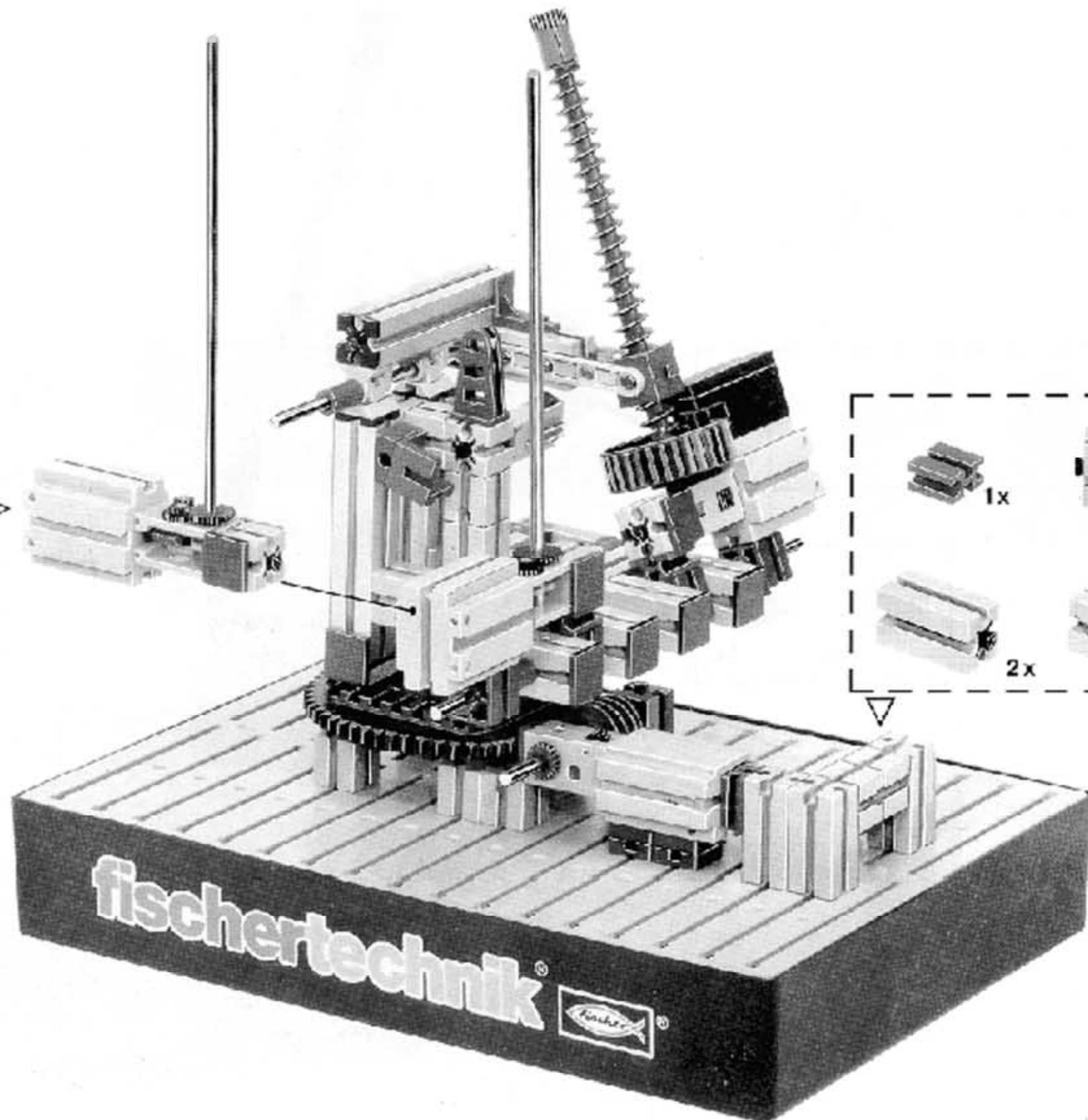
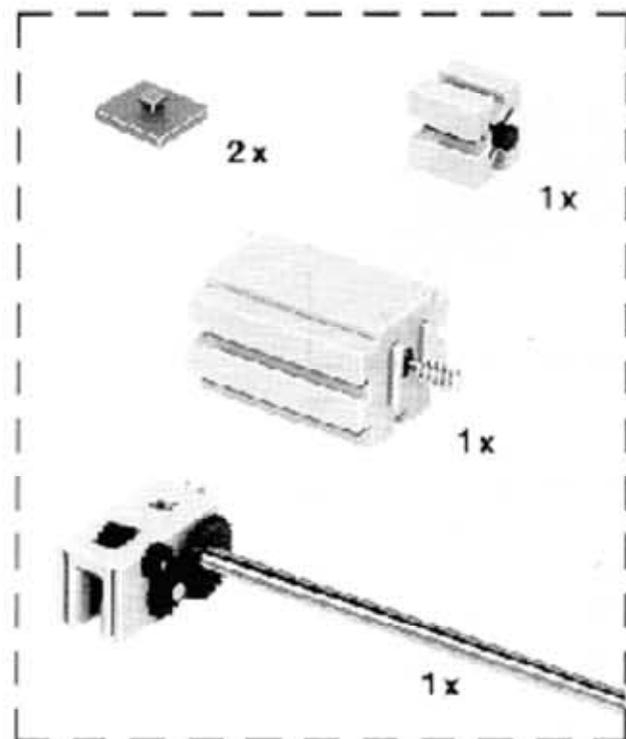
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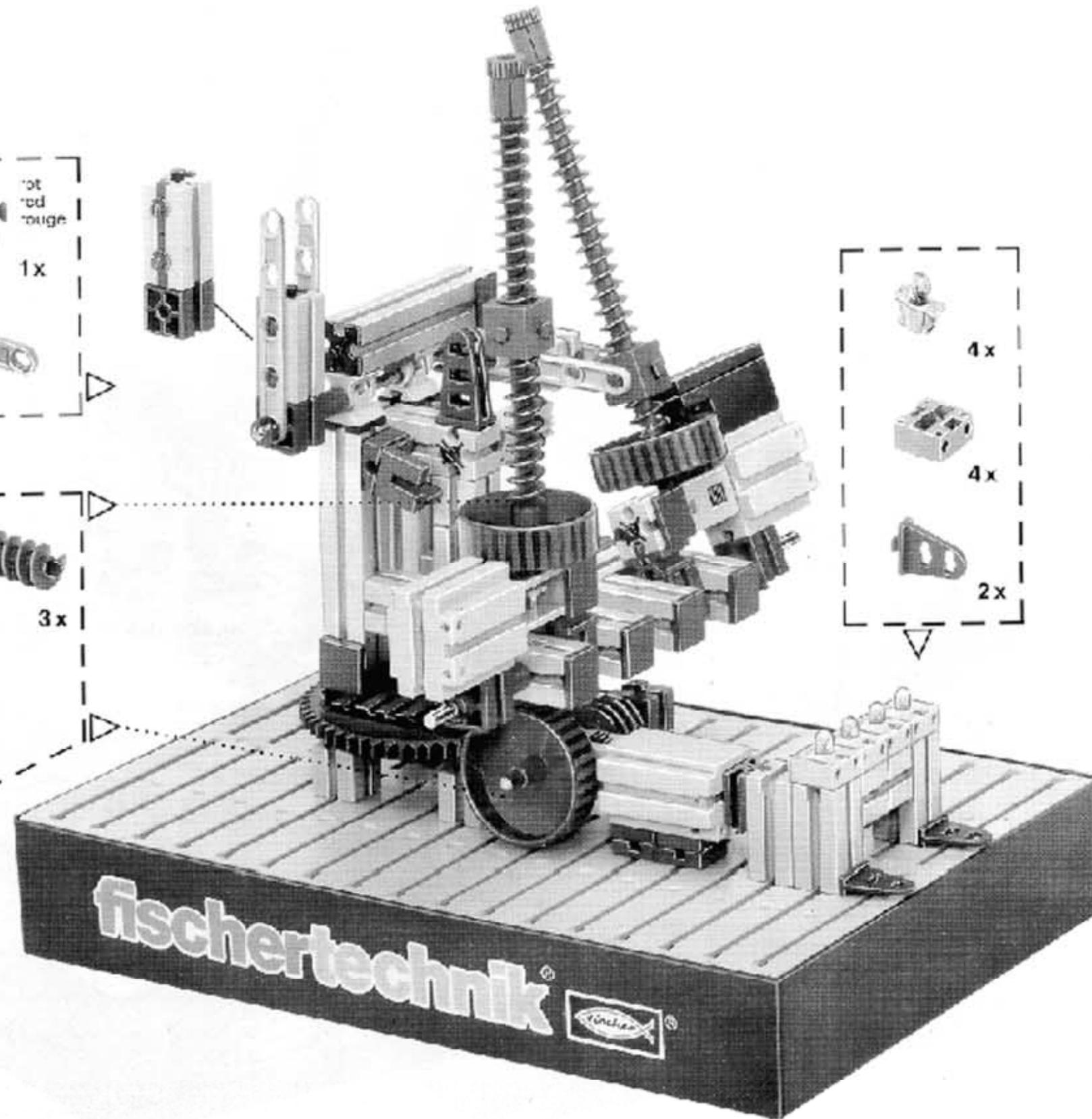
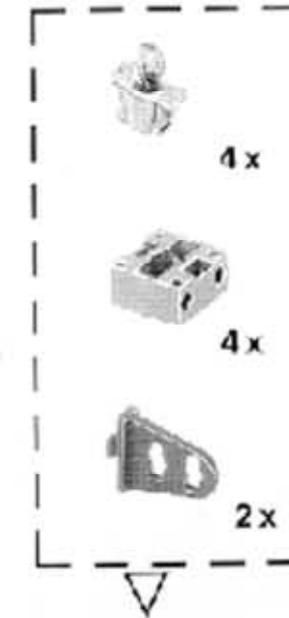
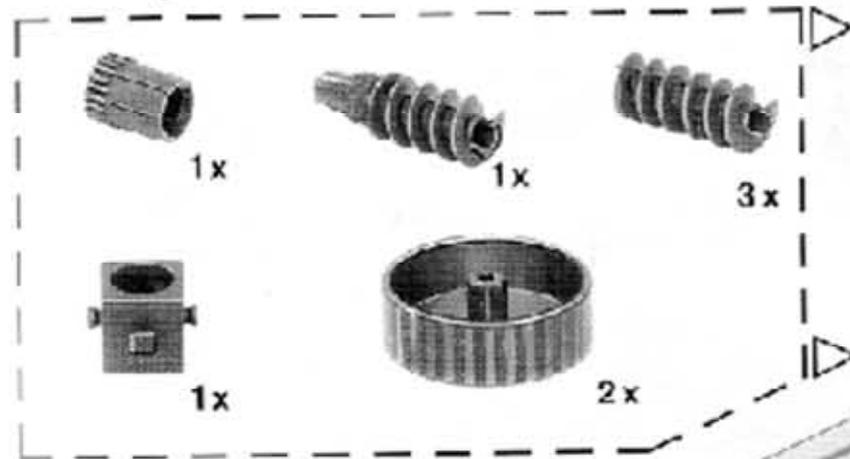
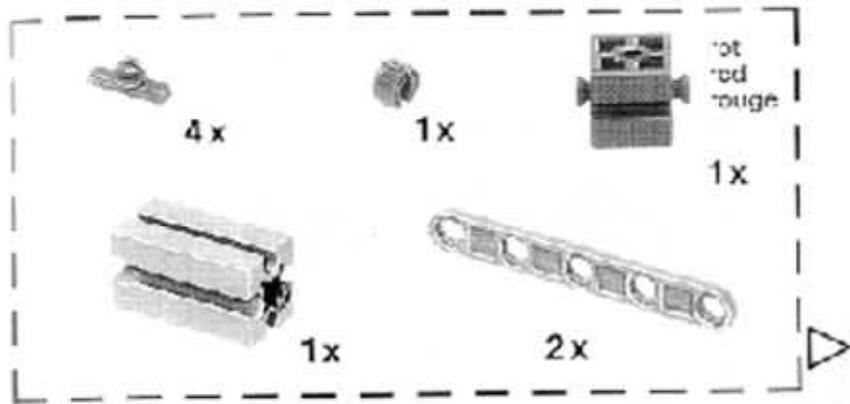


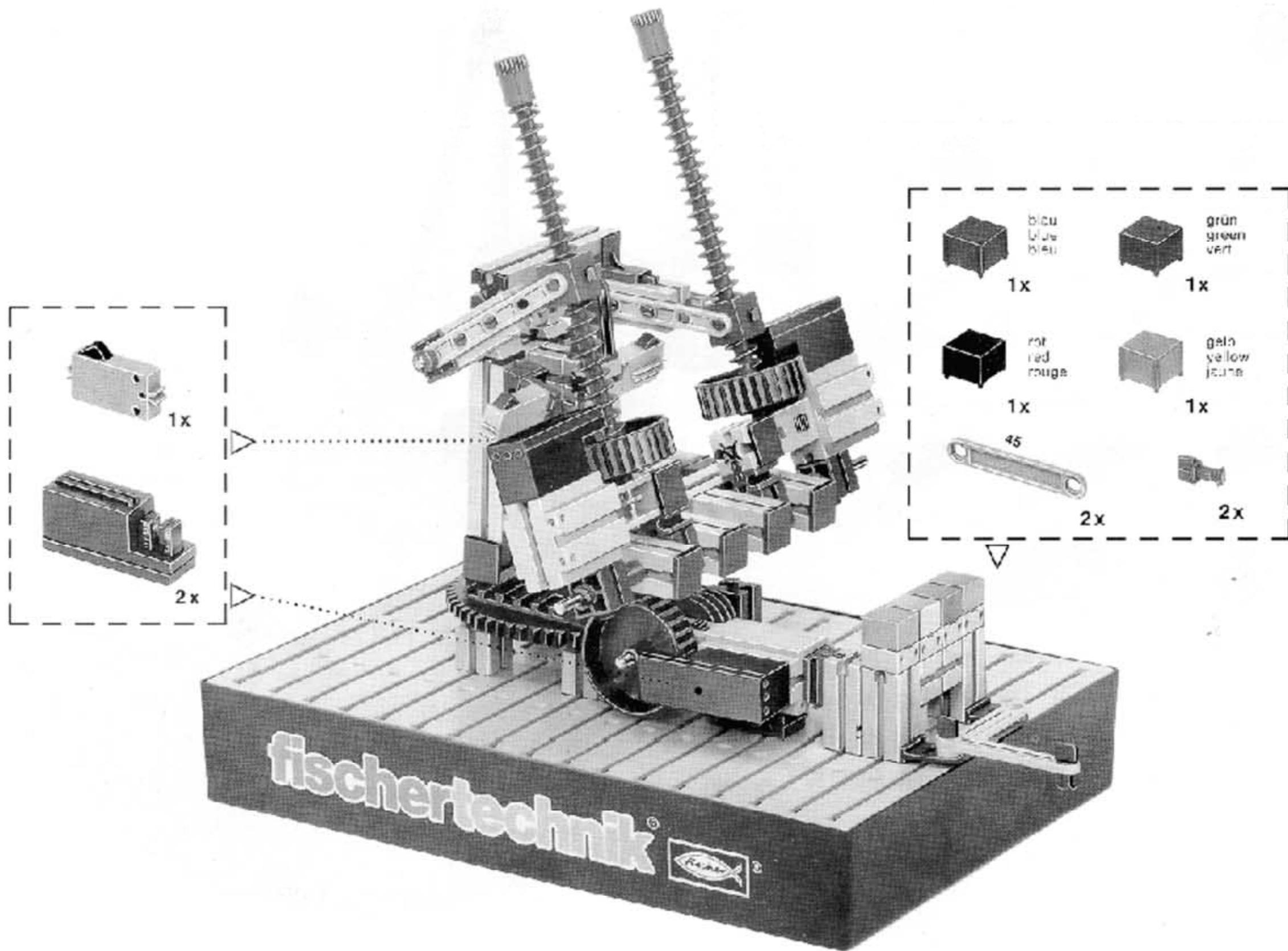
0 15 30 mm

15

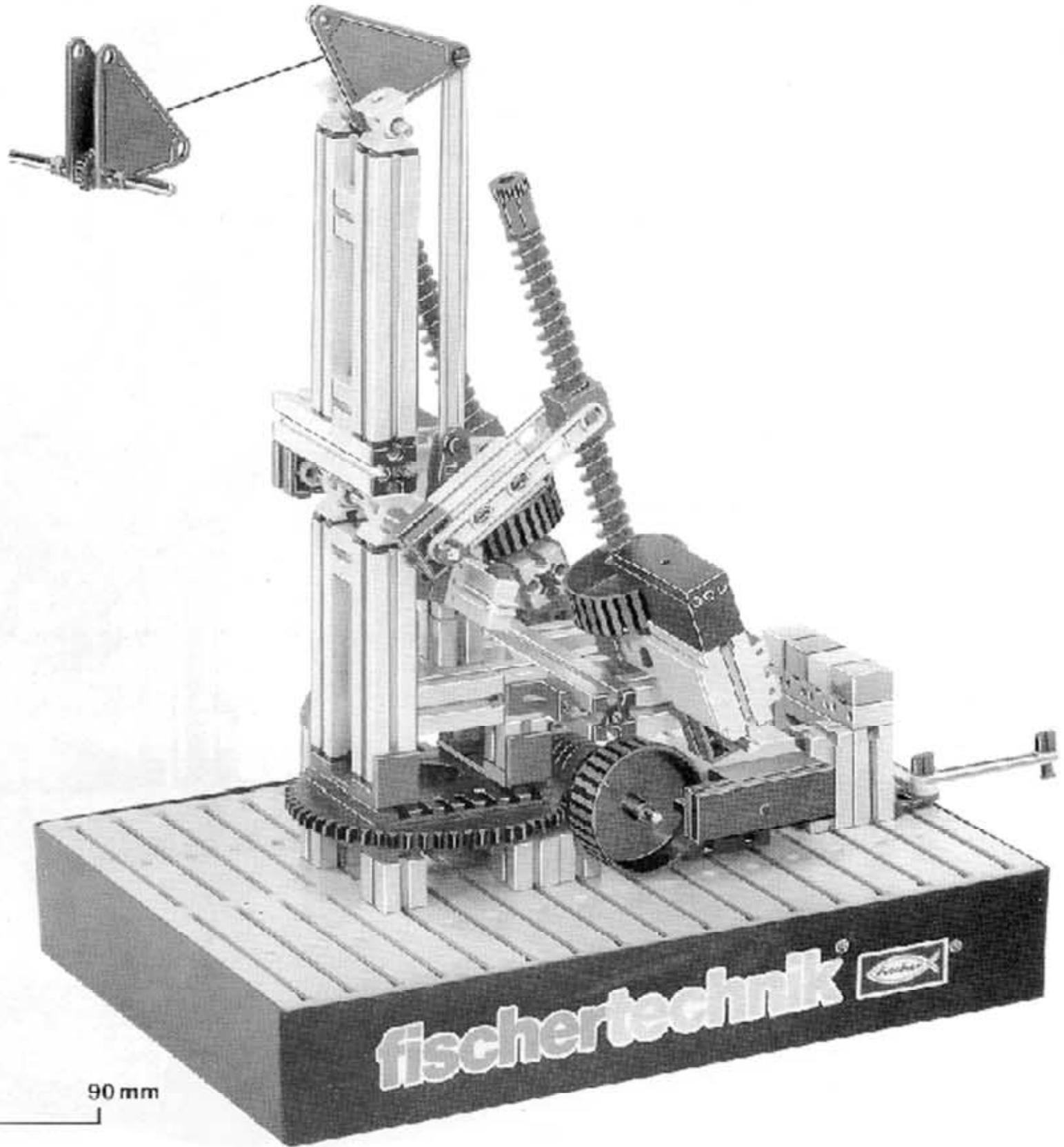
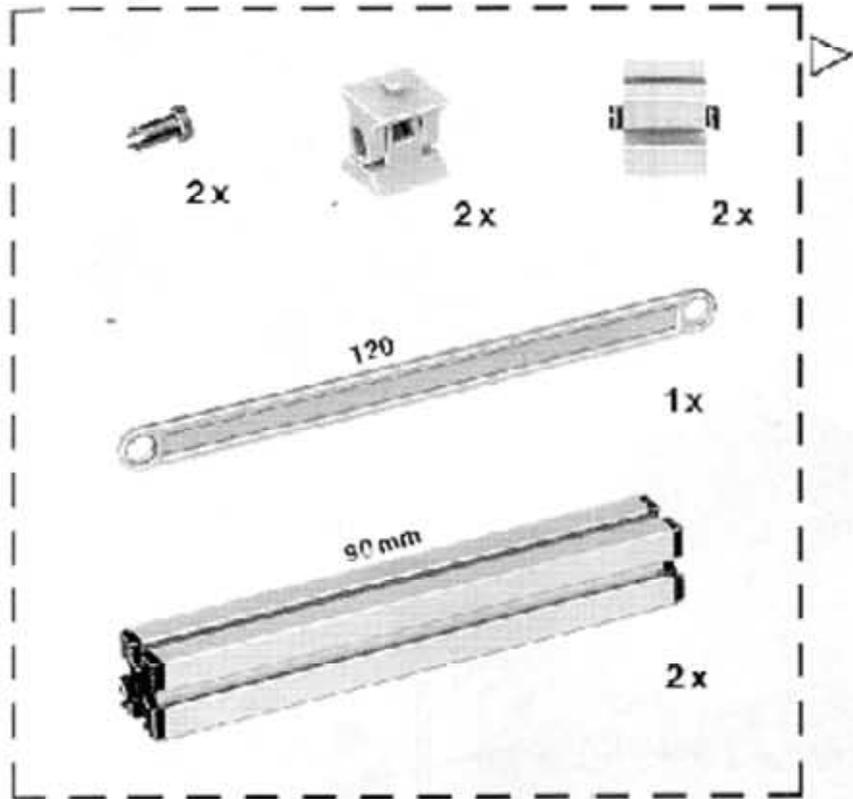
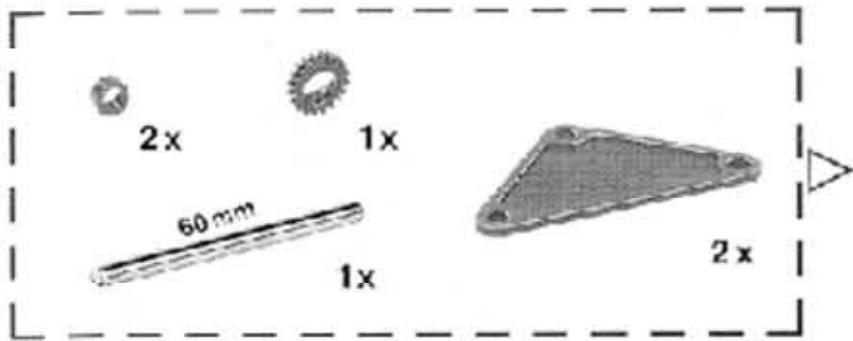


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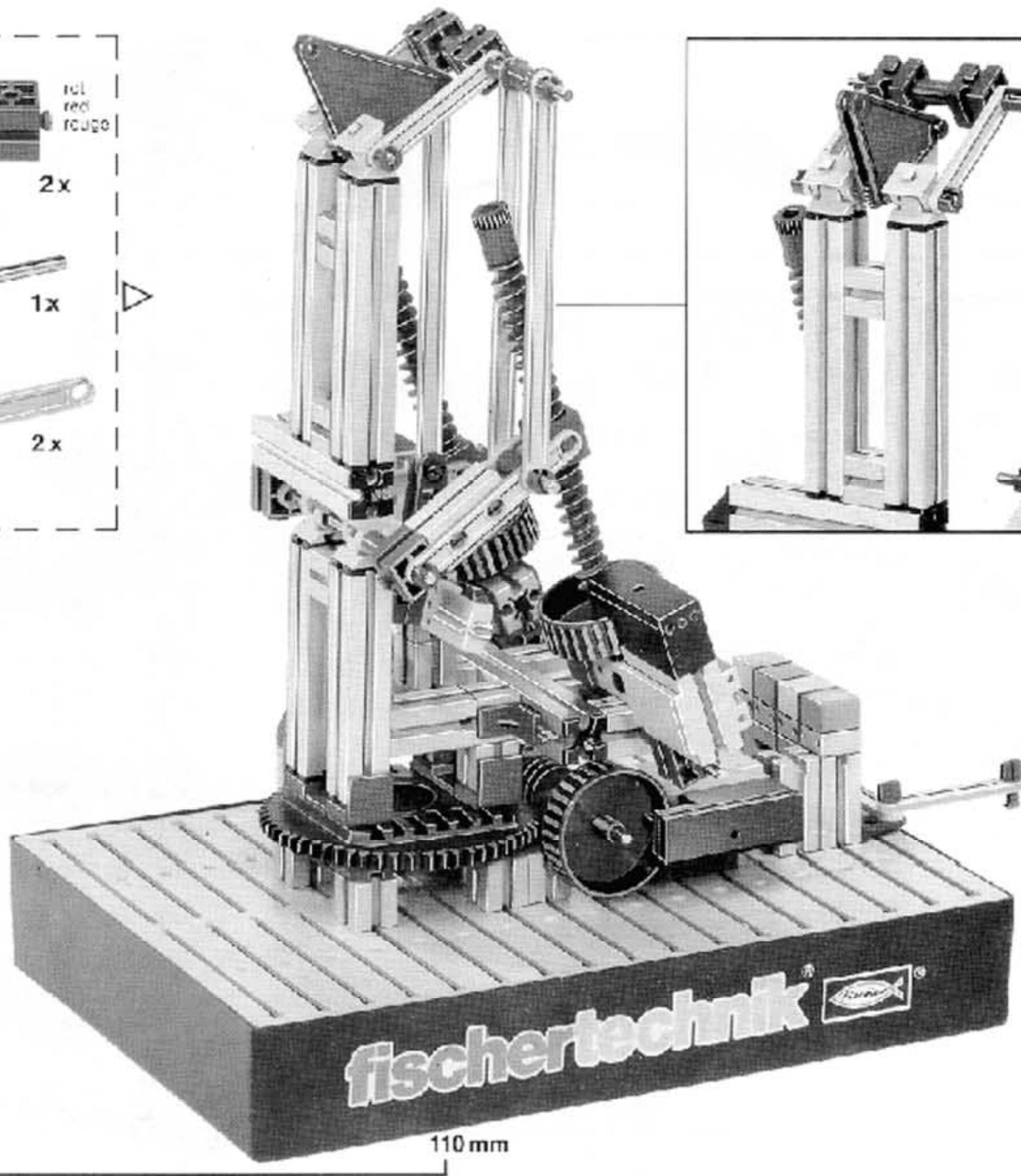
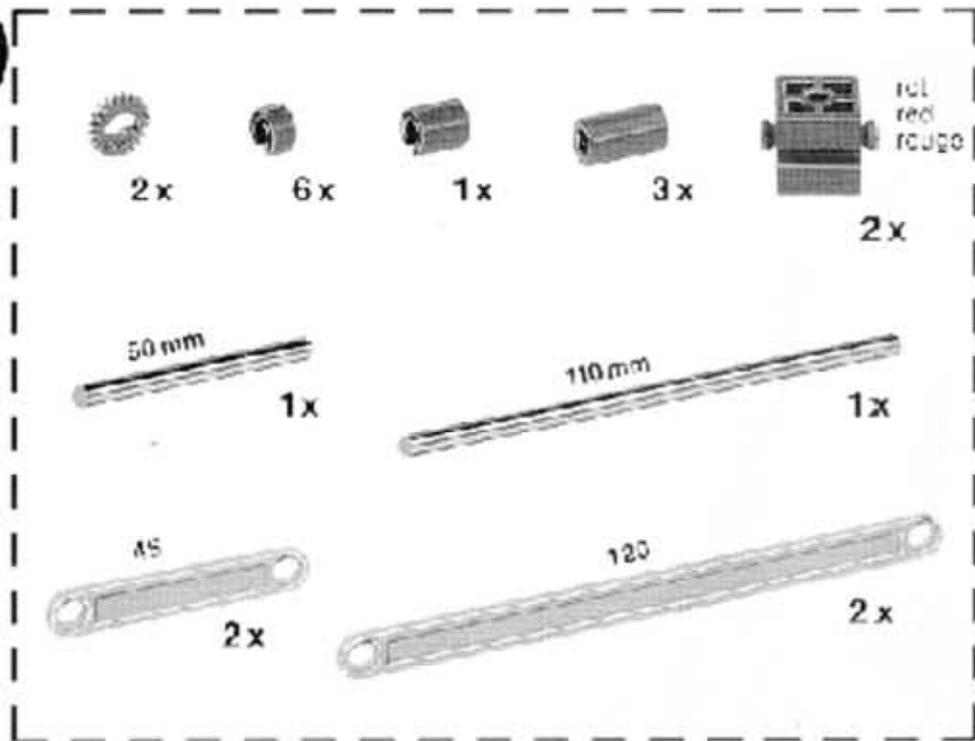




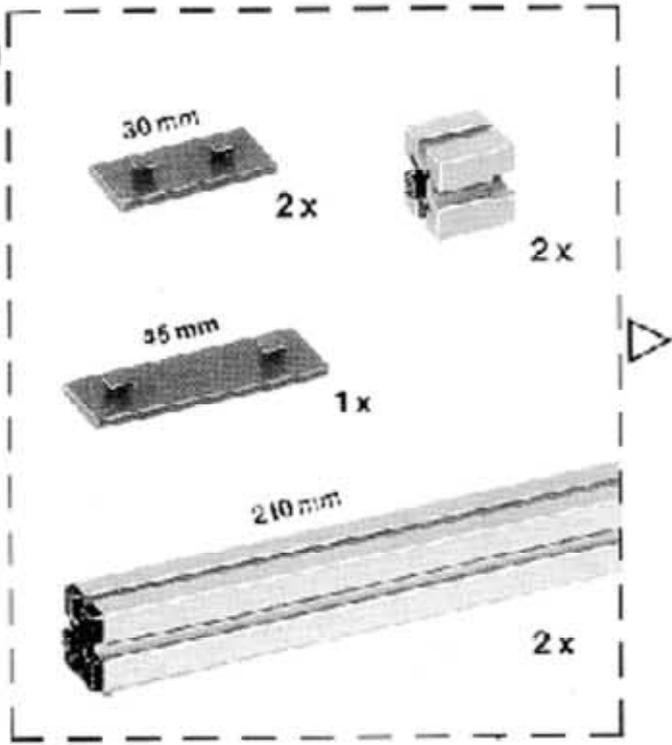
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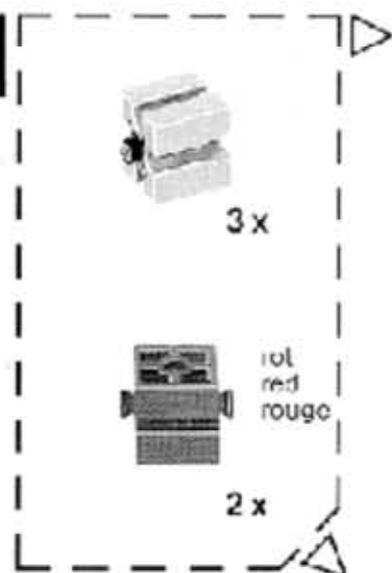
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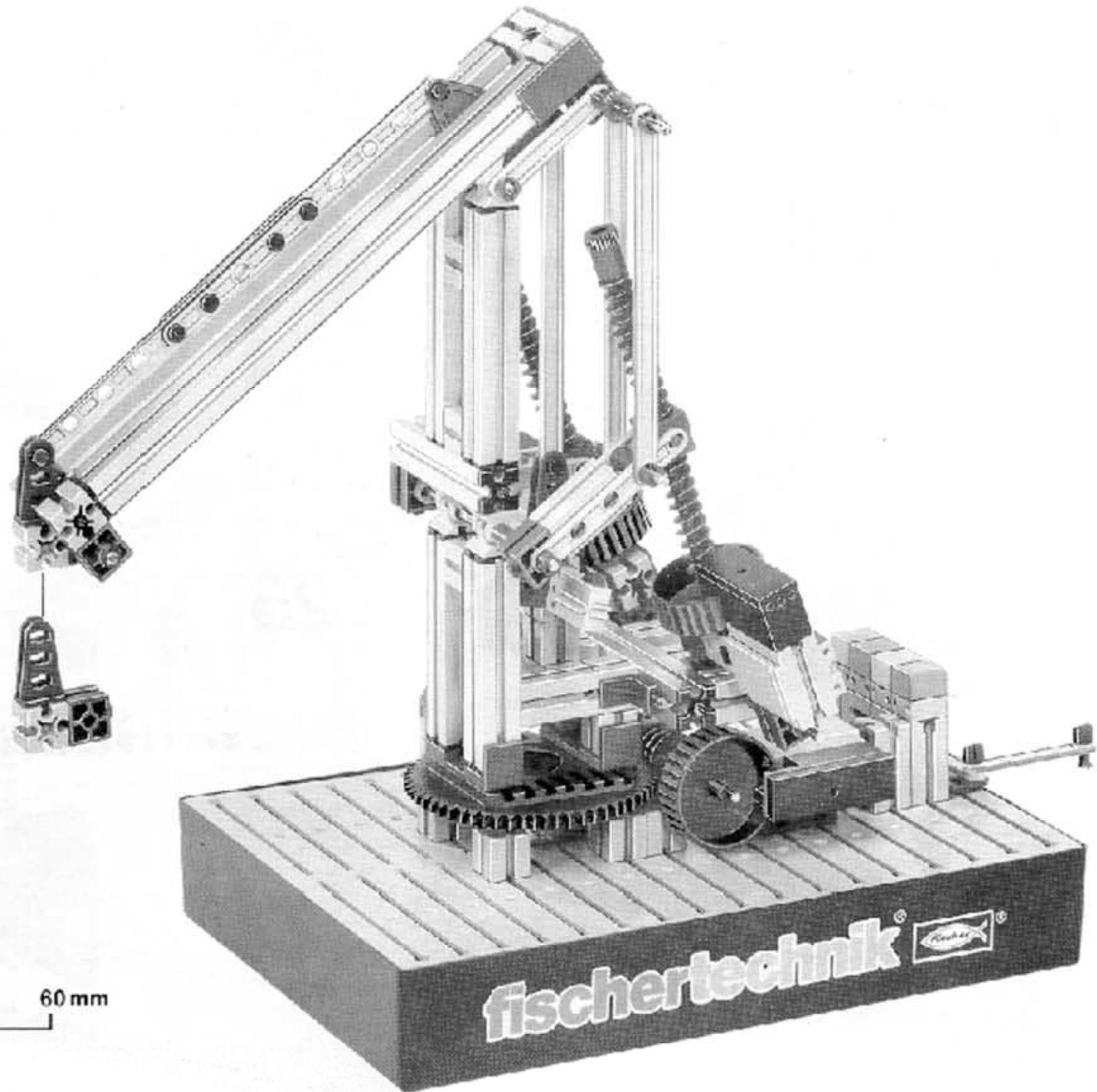
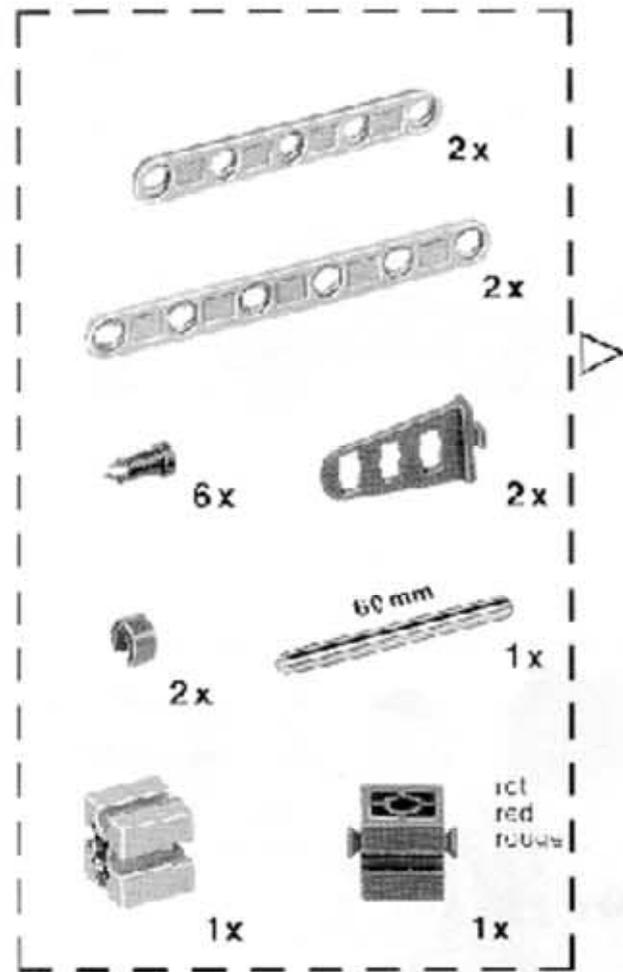


0 30 45

210 mm

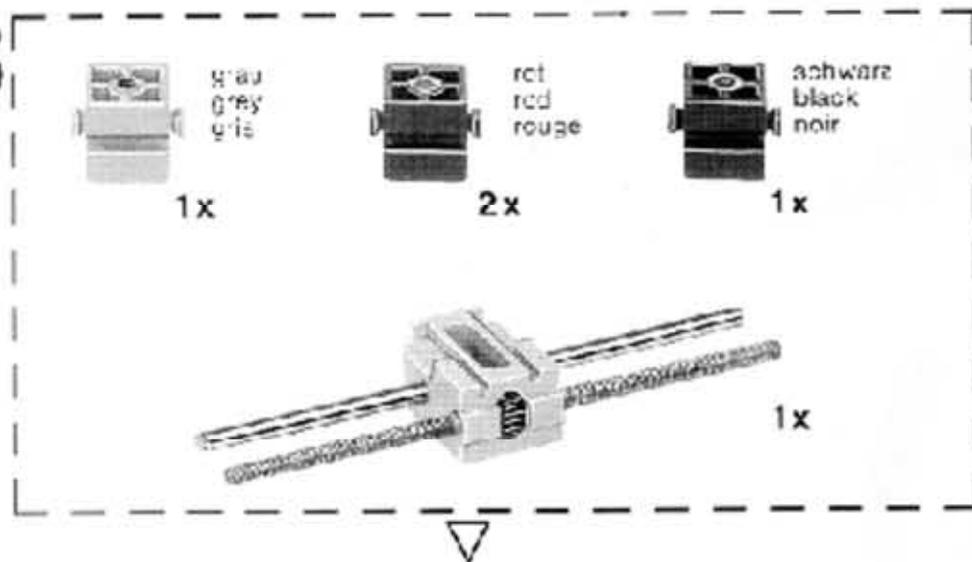
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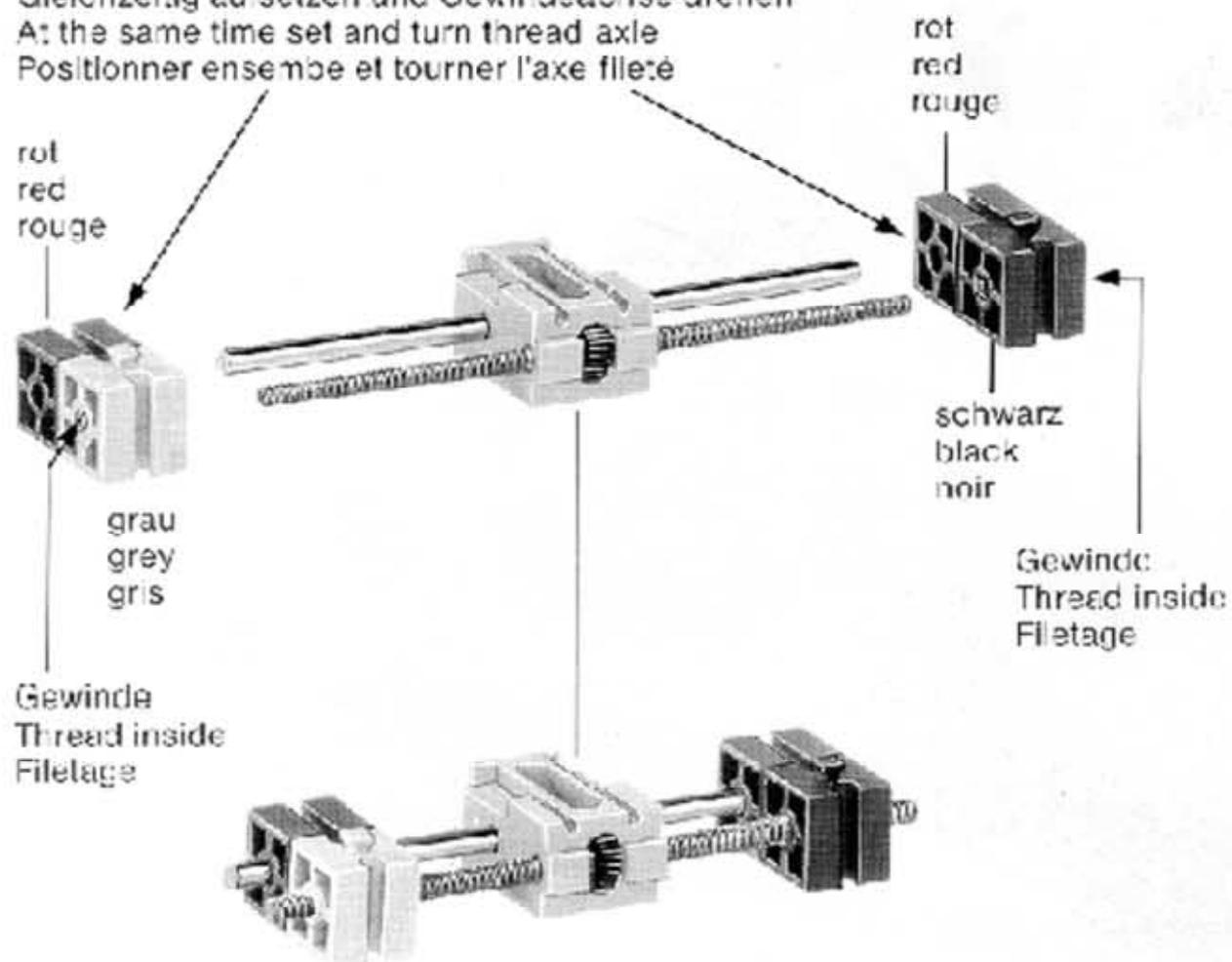


0 60 mm

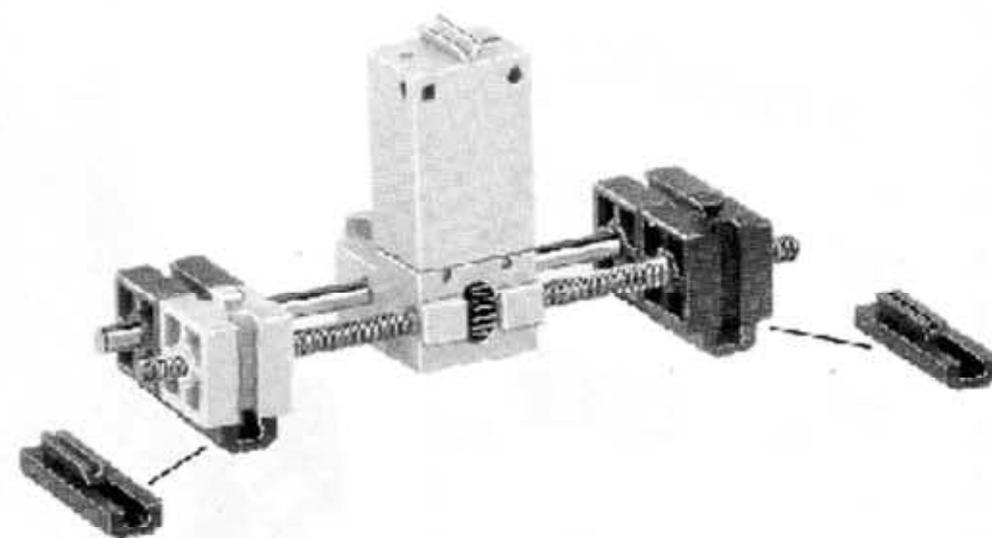
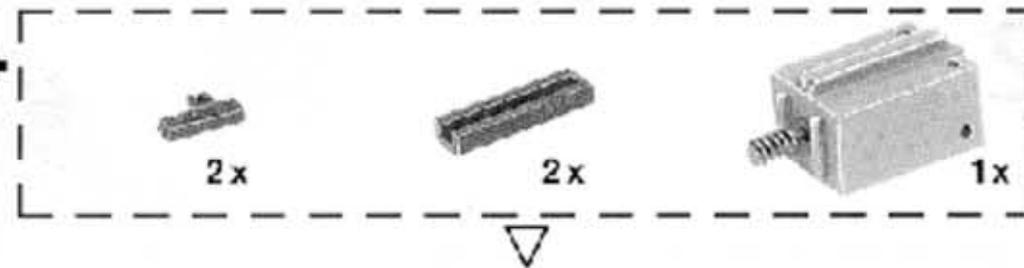
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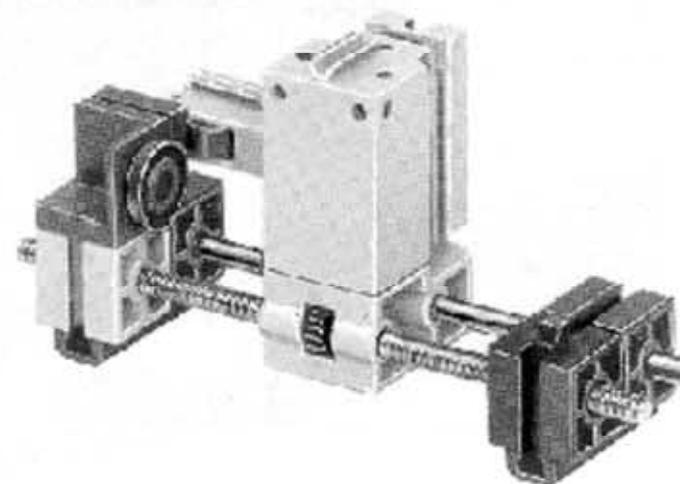
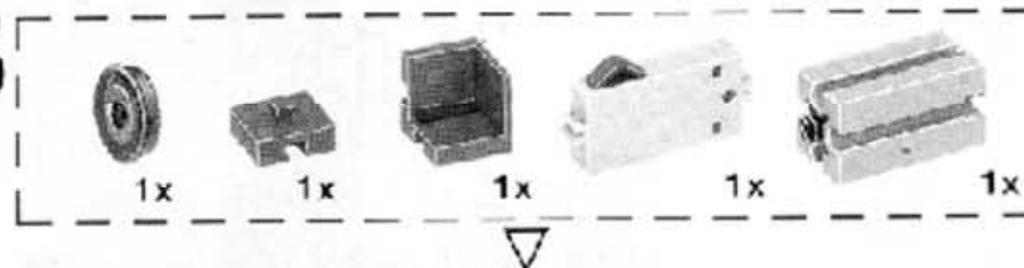
Gleichzeitig aufsetzen und Gewindeachse drehen
At the same time set and turn thread axle
Positionner ensemble et tourner l'axe fileté

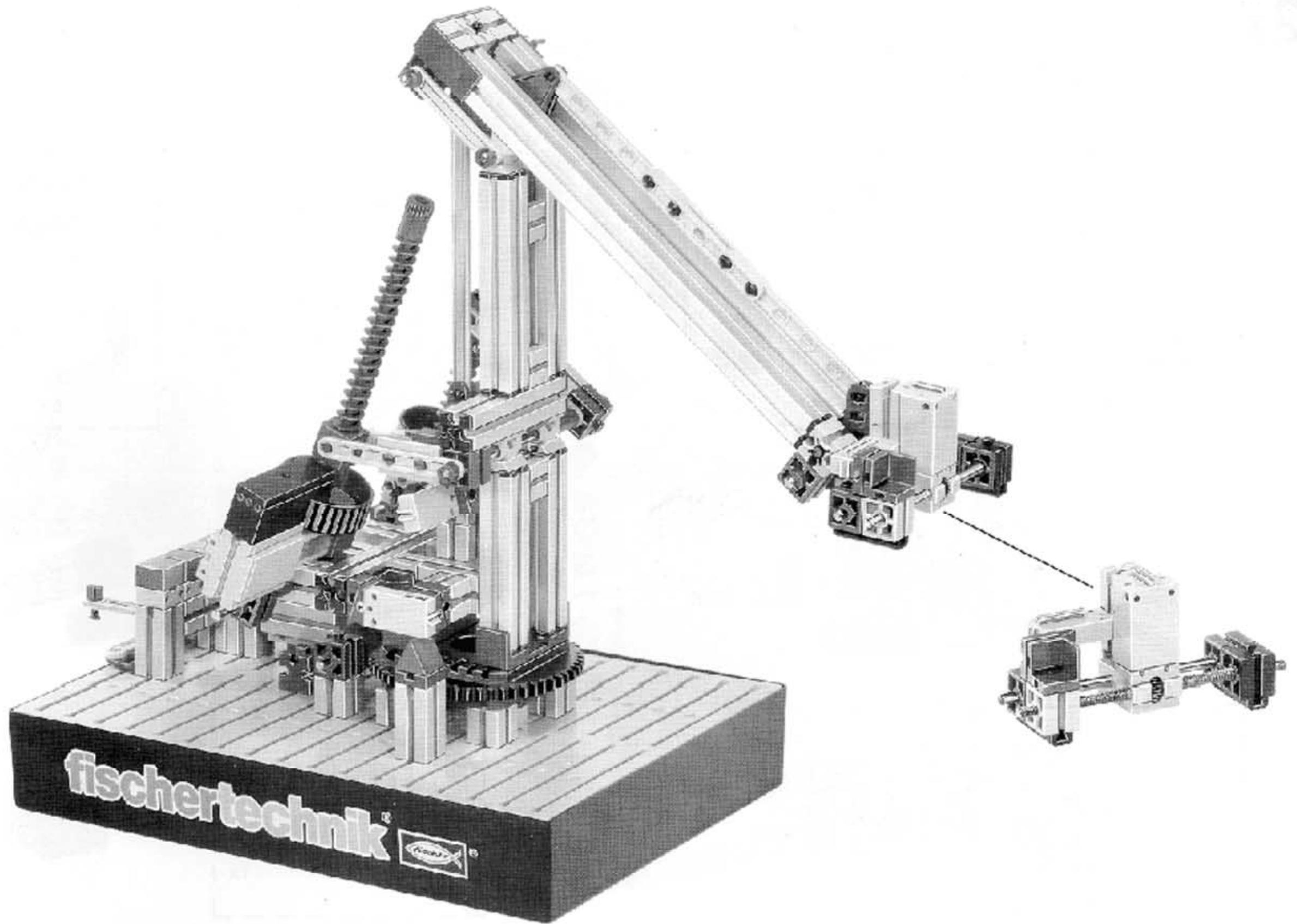


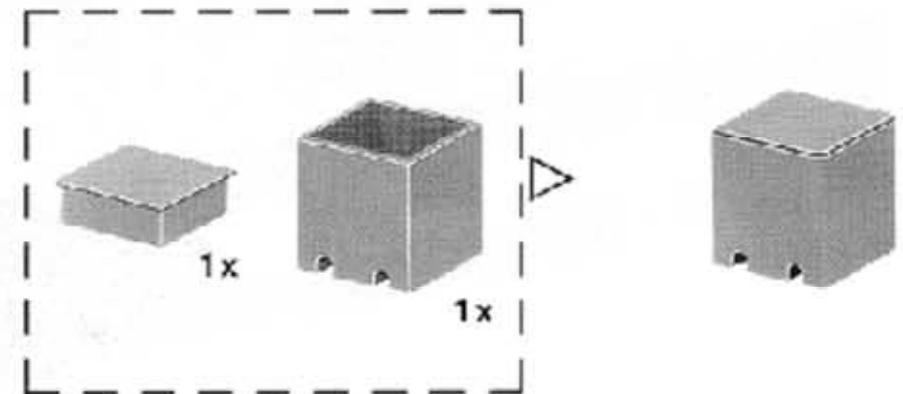
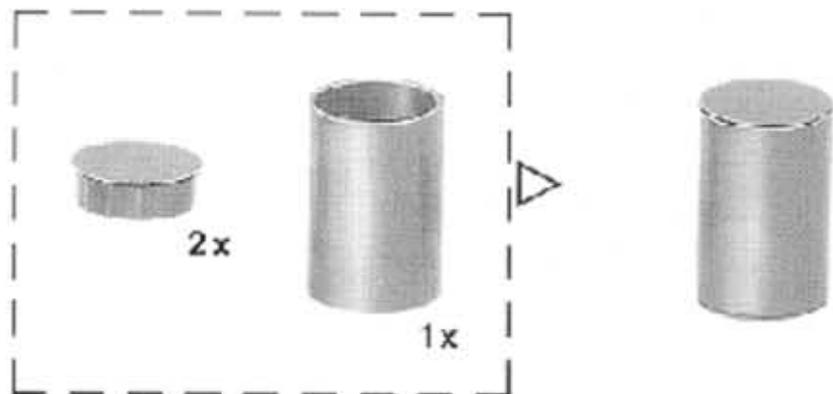
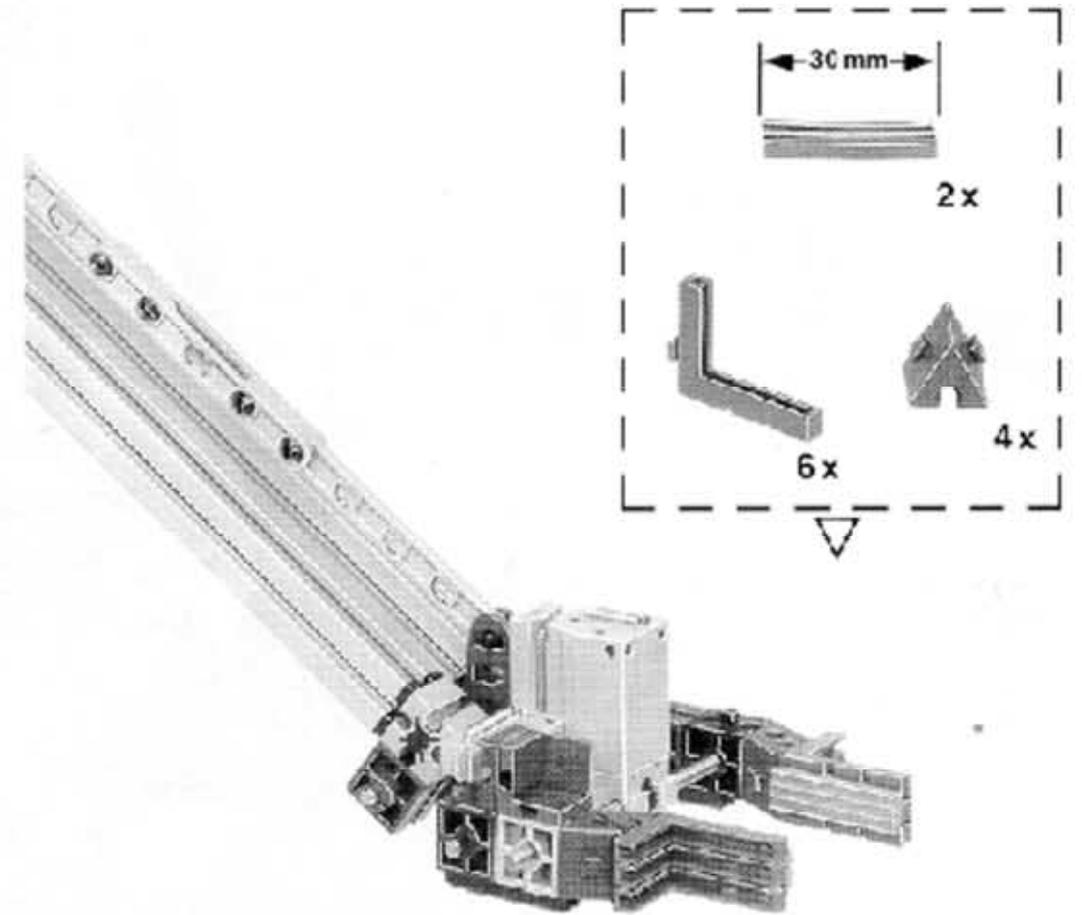
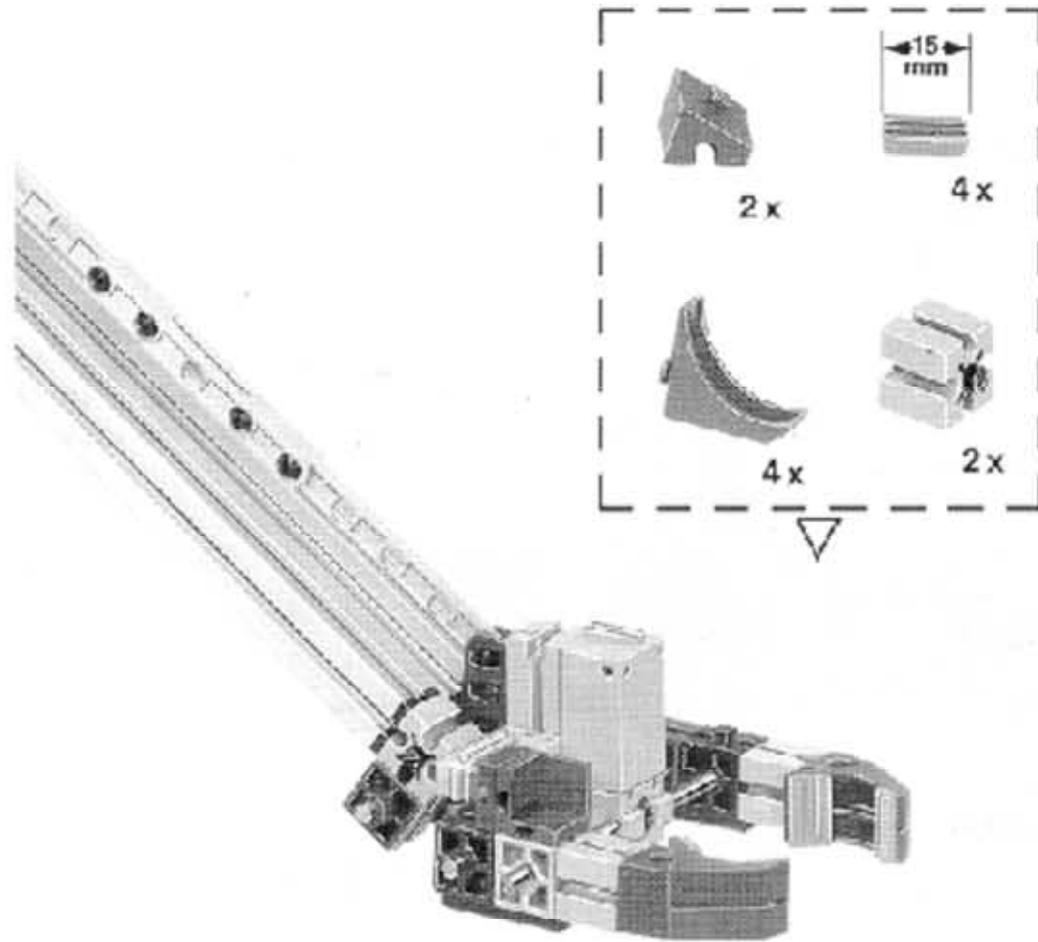
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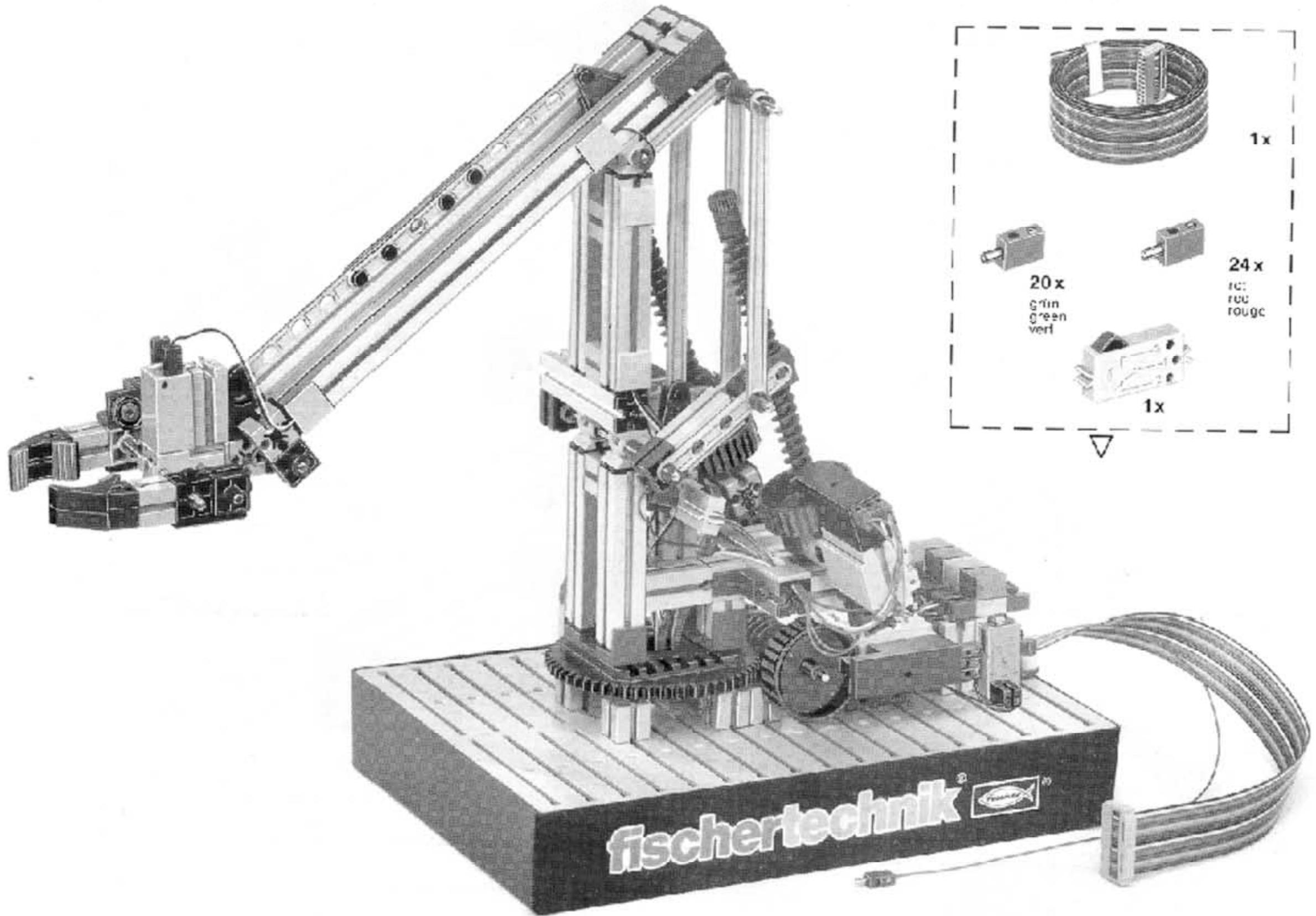


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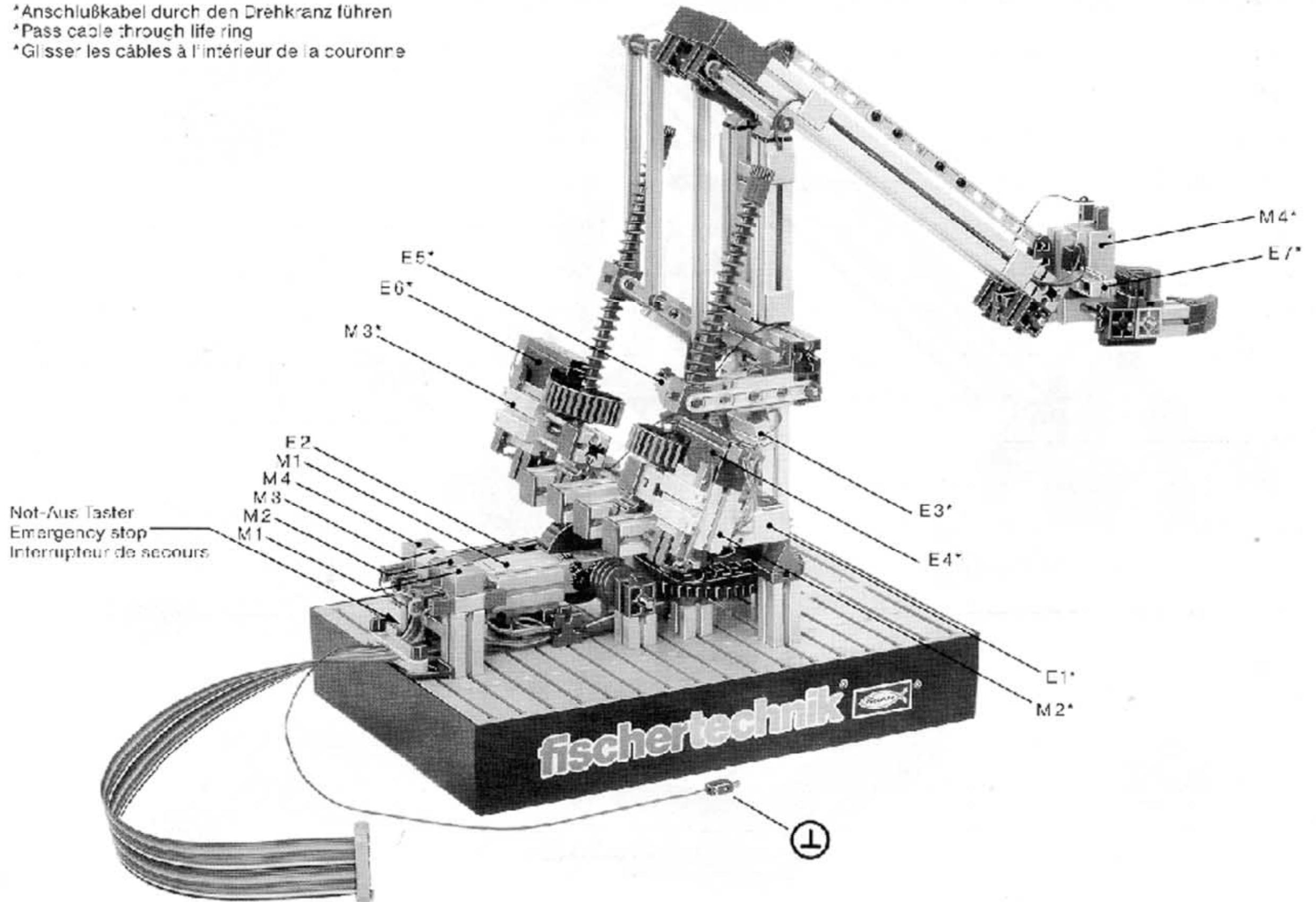






- 1x
- 20 x
grün
grün
weiß
- 24 x
rot
rot
rot
- 1x

- *Anschlußkabel durch den Drehkranz führen
- *Pass cable through life ring
- *Glisser les câbles à l'intérieur de la couronne



Verdrahtungsplan Trainingsroboter · Circuit layout Training Robot · Plan de câblage du robot d'entraînement

M4 schwarz · black · noir

M4 weiß · white · blanc

M3 grau · grey · gris

M3 violett · violet · violet

M2 blau · blue · bleu

M2 grün · green · vert

M1 gelb · yellow · jaune

M1 orange · orange · orange

+5V rot · red · rouge

E8 braun · brown · brun

E7 schwarz · black · noir

E6 weiß · white · blanc

E5 grau · grey · gris

E4 violett · violet · violet

E3 blau · blue · bleu

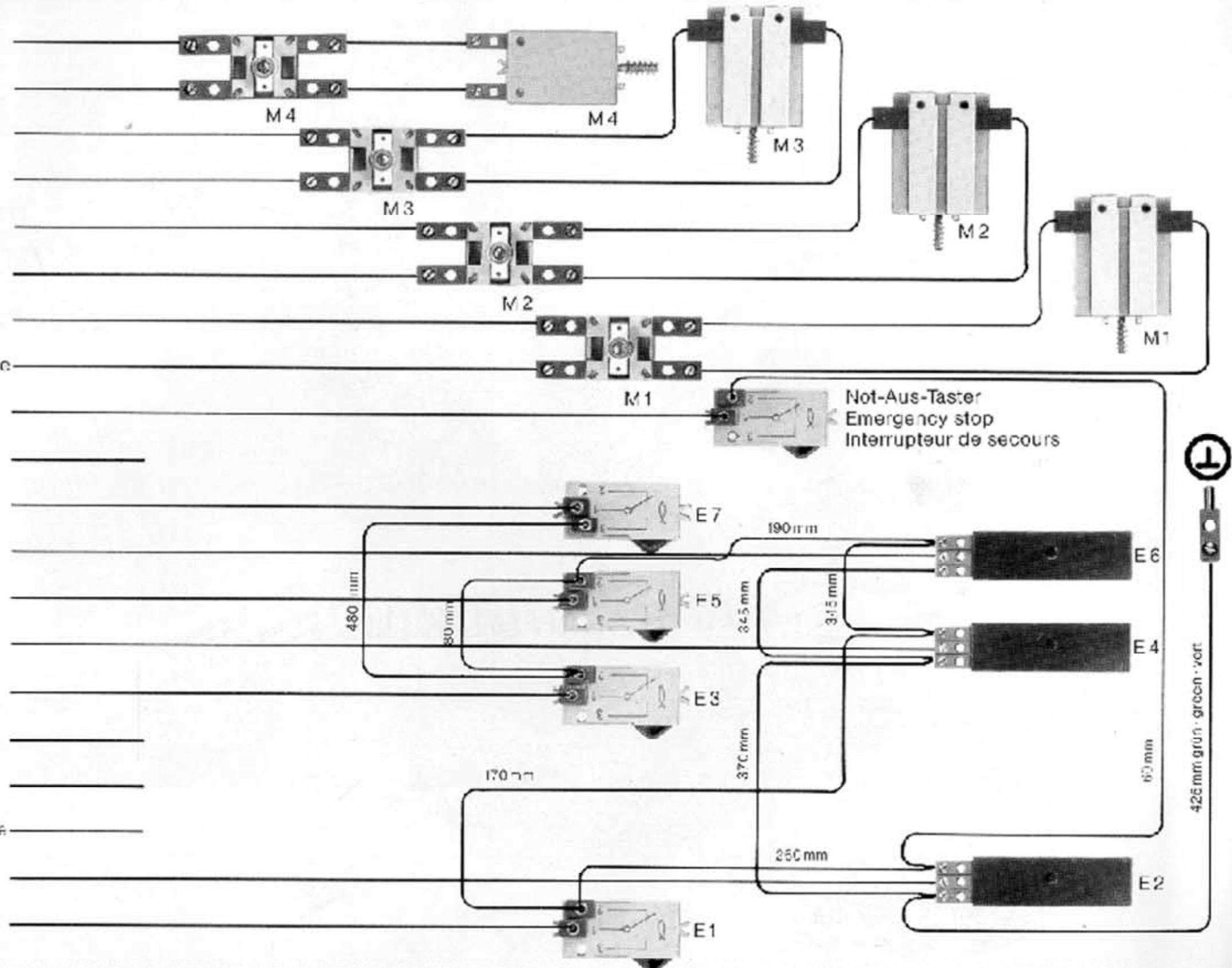
+5V grün · green · vert

EY gelb · yellow · jaune

EX orange · orange · orange

E2 rot · red · rouge

E1 braun · brown · brun



fischertechnik computing System

